Outline

• OpenGL Interface

• Introduction to OpenCL
OpenGL Interface

Utah CS 6235
by Mary Hall
OpenGL Rendering

- OpenGL buffer objects can be mapped into the CUDA address space and then used as global memory
  - Vertex buffer objects
  - Pixel buffer objects
- Allows direct visualization of data from computation
  - No device to host transfer
  - Data stays in device memory - very fast compute / viz cycle
- Data can be accessed from the kernel like any other global data (in device memory)
OpenGL Interoperability

1. Register a buffer object with CUDA
   - `cudaGLRegisterBufferObject(GLuint buffObj);`
   - OpenGL can use a registered buffer only as a source
   - Unregister the buffer prior to rendering to it by OpenGL

2. Map the buffer object to CUDA memory
   - `cudaGLMapBufferObject(void** devPtr, GLuint buffObj);`
   - Returns an address in global memory
   - Buffer must be registered prior to mapping
OpenGL Interoperability

3. Launch a CUDA kernel to process the buffer
   – Unmap the buffer object prior to use by OpenGL
     – `cudaGLUnmapBufferObject(GLuint buffObj)`;

4. Unregister the buffer object
   – `cudaGLUnregisterBufferObject(GLuint buffObj)`;
   – Optional: needed if the buffer is a render target

5. Use the buffer object in OpenGL code
Example from simpleGL in SDK

1. GL calls to create and initialize buffer, then register with CUDA:

```c
// create buffer object
glGenBuffers( 1, vbo);
glBindBuffer( GL_ARRAY_BUFFER, *vbo);

// initialize buffer object
unsigned int size = mesh_width * mesh_height * 4 * sizeof( float)*2;
glBufferData( GL_ARRAY_BUFFER, size, 0, GL_DYNAMIC_DRAW);
glBindBuffer( GL_ARRAY_BUFFER, 0);

// register buffer object with CUDA
cudaGLRegisterBufferObject(*vbo);
```
Example from simpleGL in SDK

2. Map OpenGL buffer object for writing from CUDA
   float4 *dptr;
   cudaGLMapBufferObject( (void**)&dptr, vbo));

3. Execute the kernel to compute values for dptr
   dim3 block(8, 8, 1);
   dim3 grid(mesh_width / block.x, mesh_height / block.y, 1);
   kernel<<< grid, block>>>(dptr, mesh_width, mesh_height, anim);

4. Unregister the OpenGL buffer object and return to OpenGL
   cudaGLUnmapBufferObject( vbo);
OpenCL

Patrick Cozzi
University of Pennsylvania
CIS 565 - Spring 2011

with additional material from
Joseph Kider
University of Pennsylvania
CIS 565 - Spring 2009
Processor Parallelism

CPUs
Multiple cores driving performance increases

Emerging Intersection

Multi-processor programming – e.g. OpenMP

Heterogeneous Computing

GPUs
Increasingly general purpose data-parallel computing

Graphics APIs and Shading Languages

OpenCL is a programming framework for heterogeneous compute resources
OpenCL

- **Open Compute Language**
- For heterogeneous parallel-computing systems
- Cross-platform
  - Implementations for
    - ATI GPUs
    - NVIDIA GPUs
    - x86 CPUs
  - Is cross-platform really *one size fits all*?

OpenCL

• Standardized
• Initiated by Apple
• Developed by the Khronos Group
OpenCL Working Group

- Diverse industry participation
  - Processor vendors, system OEMs, middleware vendors, application developers

- Many industry-leading experts involved in OpenCL’s design
  - A healthy diversity of industry perspectives

- Apple made initial proposal and is very active in the working group
  - Serving as specification editor
OpenCL Timeline

- **Six months from proposal to released OpenCL 1.0 specification**
  - Due to a strong initial proposal and a shared commercial incentive

- **Multiple conformant implementations shipping**
  - Apple’s Mac OS X Snow Leopard now ships with OpenCL

- **18 month cadence between OpenCL 1.0 and OpenCL 1.1**
  - Backwards compatibility protect software investment

---

Version 2.0 released in 2013
OpenGL-based Ecosystem

Desktop Visual Computing
OpenGL and OpenCL have direct interoperability. OpenCL objects can be created from OpenGL Textures, Buffer Objects and Renderbuffers

Mobile Visual Computing
Compute, graphics and AV APIs interoperate through EGL

Roadmap Convergence
OpenGL 4.0 and OpenGL ES 2.0 are both streamlined, programmable pipelines. GL and ES working groups are working on convergence. WebGL is a positive pressure for portable 3D content on all platforms
Design Goals of OpenCL

- Use all computational resources in the system
  - GPUs and CPUs as peers
  - Data- and task-parallel computing

- Efficient parallel programming model
  - Based on C
  - Abstract the specifics of underlying hardware
  - Define maximum allowable errors of math functions

- Drive future hardware requirements
OpenCL

- API similar to OpenGL
- Based on the C language
- Easy transition form CUDA to OpenCL
OpenCL and CUDA

• Many OpenCL features have a one to one mapping to CUDA features

• OpenCL
  – More complex platform and device management
  – More complex kernel launch

➤ OpenCL is more complex due to its support for multiplatform and multivendor portability
OpenCL and CUDA

• *Compute Unit* (CU) corresponds to
  – CUDA streaming multiprocessor (SMs)
  – CPU core
  – etc.

• *Processing Element* corresponds to
  – CUDA streaming processor (SP)
  – CPU ALU
OpenCL and CUDA

# OpenCL and CUDA

<table>
<thead>
<tr>
<th>CUDA</th>
<th>OpenCL</th>
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<tr>
<td>Kernel</td>
<td>Kernel</td>
</tr>
<tr>
<td>Host program</td>
<td>Host program</td>
</tr>
<tr>
<td>Thread</td>
<td>Work item</td>
</tr>
<tr>
<td>Block</td>
<td>Work group</td>
</tr>
<tr>
<td>Grid</td>
<td>NDRange (index space)</td>
</tr>
</tbody>
</table>
OpenCL and CUDA

- **Work Item** (CUDA *thread*) - executes kernel code
- **Index Space** (CUDA *grid*) - defines work items and how data is mapped to them
- **Work Group** (CUDA *block*) - work items in a work group can synchronize
OpenCL and CUDA

- CUDA: `threadIdx` and `blockIdx`
  - Combine to create a global thread ID
  - Example
    - `blockIdx.x * blockDim.x + threadIdx.x`
OpenCL and CUDA

• OpenCL: each thread has a unique global index
  – Retrieve with \texttt{get\_global\_id()}
OpenCL and CUDA

<table>
<thead>
<tr>
<th>CUDA</th>
<th>OpenCL</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>gridDim.x</code></td>
<td><code>get_num_groups(0)</code></td>
</tr>
<tr>
<td><code>blockIdx.x</code></td>
<td><code>get_group_id(0)</code></td>
</tr>
<tr>
<td><code>blockDim.x</code></td>
<td><code>get_local_size(0)</code></td>
</tr>
<tr>
<td><code>gridDim.x * blockDim.x</code></td>
<td><code>get_global_size(0)</code></td>
</tr>
</tbody>
</table>
OpenCL and CUDA

- Recall CUDA:
OpenCL and CUDA

- In OpenCL:

  - `get_local_size(0)`
  - `get_global_size(0)`
Kernels: Work-item and Work-group Example

Dimension: 2
Global size: 32x32 = 1024
Num of groups: 16

Local id: (4, 2)
Global id: (28, 10)
Workgroup id: (3, 1)
Local size: 8x8 = 64
OpenCL and CUDA

• Recall the CUDA memory model:
OpenCL and CUDA

• In OpenCL:
## OpenCL and CUDA

<table>
<thead>
<tr>
<th>CUDA</th>
<th>OpenCL</th>
</tr>
</thead>
<tbody>
<tr>
<td>Global memory</td>
<td>Global memory</td>
</tr>
<tr>
<td>Constant memory</td>
<td>Constant memory</td>
</tr>
<tr>
<td>Shared memory</td>
<td>Local memory</td>
</tr>
<tr>
<td>Local memory</td>
<td>Private memory</td>
</tr>
</tbody>
</table>

![Diagram showing the memory hierarchy in CUDA and OpenCL](image)

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## OpenCL and CUDA

<table>
<thead>
<tr>
<th>CUDA</th>
<th>Host Access</th>
<th>Device Access</th>
<th>OpenCL</th>
</tr>
</thead>
<tbody>
<tr>
<td>Global memory</td>
<td>Dynamic allocation; read/write access</td>
<td>No allocation; read/write access by all work items in all work groups; large and slow but may be cached in some devices</td>
<td>Global memory</td>
</tr>
<tr>
<td>Constant memory</td>
<td>Dynamic allocation; read/write access</td>
<td>Static allocation; read only access by all work items</td>
<td>Constant memory</td>
</tr>
<tr>
<td>Shared memory</td>
<td>Dynamic allocation; no access</td>
<td>Static allocation; shared read/write access by all work items in a work group</td>
<td>Local memory</td>
</tr>
<tr>
<td>Local memory</td>
<td>No allocation; no access</td>
<td>Static allocation; read/write access by a single work item</td>
<td>Private memory</td>
</tr>
</tbody>
</table>
(Constant Memory in CUDA)

```c
__constant__ float constMemPool[16384];

__global__ void kernel(...)
{
    float x = constMemPool[tx];
    ....
}

int hostFunction()
{
    ....
    cudaMemcpyToSymbol(constMemPool, &dim, size_dim);
}```
OpenCL and CUDA

- Both also have *Fences*
  - In OpenCL
    - `mem_fence()`
    - `read_mem_fence()`
    - `write_mem_fence()`
OpenCL Fence Examples

• \texttt{mem\_fence(\texttt{CLK}\_\texttt{LOCAL}\_\texttt{MEM}\_\texttt{FENCE}}}
  \texttt{and/or \texttt{CLK}\_\texttt{GLOBAL}\_\texttt{MEM}\_\texttt{FENCE})}
  - waits until all reads/writes to local and/or global memory made by the calling work item prior to \texttt{mem\_fence()} are visible to all threads in the \texttt{work\_group}

• \texttt{barrier(\texttt{CLK}\_\texttt{LOCAL}\_\texttt{MEM}\_\texttt{FENCE}}}
  \texttt{and/or \texttt{CLK}\_\texttt{GLOBAL}\_\texttt{MEM}\_\texttt{FENCE})}
  - waits until all work-items in the work-group have reached this point and calls \texttt{mem\_fence(\texttt{CLK}\_\texttt{LOCAL}\_\texttt{MEM}\_\texttt{FENCE}} \texttt{and/or} \texttt{CLK}\_\texttt{GLOBAL}\_\texttt{MEM}\_\texttt{FENCE})}
Programming kernels: OpenCL C Language

- A subset of ISO C99
  - But without some C99 features such as standard C99 headers, function pointers, recursion, variable length arrays, and bit fields

- A superset of ISO C99 with additions for:
  - Work-items and workgroups
  - Vector types
  - Synchronization
  - Address space qualifiers

- Also includes a large set of built-in functions
  - Image manipulation
  - Work-item manipulation,
  - Specialized math routines, etc.
Porting CUDA to OpenCL™

- Qualifiers

<table>
<thead>
<tr>
<th>C for CUDA Terminology</th>
<th>OpenCL™ Terminology</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>global</strong> function</td>
<td>__kernel function</td>
</tr>
<tr>
<td><strong>device</strong> function</td>
<td>function (no qualifier required)</td>
</tr>
<tr>
<td><strong>constant</strong> variable declaration</td>
<td>__constant variable declaration</td>
</tr>
<tr>
<td><strong>device</strong> variable declaration</td>
<td>__global variable declaration</td>
</tr>
<tr>
<td><strong>shared</strong> variable declaration</td>
<td>__local variable declaration</td>
</tr>
</tbody>
</table>
## Data Types

<table>
<thead>
<tr>
<th>Scalar Type</th>
<th>Vector Type ((n = 2, 4, 8, 16))</th>
<th>API Type for host app</th>
</tr>
</thead>
<tbody>
<tr>
<td>char, uchar</td>
<td>charn, ucharh</td>
<td>cl_char(&lt;n&gt;), cl_uchar(&lt;n&gt;)</td>
</tr>
<tr>
<td>short, ushort</td>
<td>shortn, ushortn</td>
<td>cl_short(&lt;n&gt;), cl_ushort(&lt;n&gt;)</td>
</tr>
<tr>
<td>int, uint</td>
<td>intn, uintn</td>
<td>cl_int(&lt;n&gt;), cl_uint(&lt;n&gt;)</td>
</tr>
<tr>
<td>long, ulong</td>
<td>longn, ulongn</td>
<td>cl_long(&lt;n&gt;), cl_ulong(&lt;n&gt;)</td>
</tr>
<tr>
<td>float</td>
<td>floatn</td>
<td>cl_float(&lt;n&gt;)</td>
</tr>
</tbody>
</table>
Accessing Vector Components

- Accessing components for vector types with 2 or 4 components
  - <vector2>.xy, <vector4>.xyzw

```c
float2 pos;
pos.x = 1.0f;
pos.y = 1.0f;
pos.z = 1.0f; // illegal since vector only has 2 components

float4 c;
c.x = 1.0f;
c.y = 1.0f;
c.z = 1.0f;
c.w = 1.0f;
```
## Accessing Vector with Numeric Index

<table>
<thead>
<tr>
<th>Vector components</th>
<th>Numeric indices</th>
</tr>
</thead>
<tbody>
<tr>
<td>2 components</td>
<td>0, 1</td>
</tr>
<tr>
<td>4 components</td>
<td>0, 1, 2, 3</td>
</tr>
<tr>
<td>8 components</td>
<td>0, 1, 2, 3, 4, 5, 6, 7</td>
</tr>
<tr>
<td>16 components</td>
<td>0, 1, 2, 3, 4, 5, 6, 7, 8, 9, a, A, b, B, c, C, e, E, f, F</td>
</tr>
</tbody>
</table>

```c
float8 f;
f.s0 = 1.0f; // the 1st component in the vector
f.s7 = 1.0f; // the 8th component in the vector

float16 x;
f.sa = 1.0f; // or f.sA is the 10th component in the vector
f.sF = 1.0f; // or f.sF is the 16th component in the vector
```
Handy addressing of Vector Components

<table>
<thead>
<tr>
<th>Vector access suffix</th>
<th>Returns</th>
</tr>
</thead>
<tbody>
<tr>
<td>.lo</td>
<td>Returns the lower half of a vector</td>
</tr>
<tr>
<td>.hi</td>
<td>Returns the upper half of a vector</td>
</tr>
<tr>
<td>.odd</td>
<td>Returns the odd components of a vector</td>
</tr>
<tr>
<td>.even</td>
<td>Returns the even components of a vector</td>
</tr>
</tbody>
</table>

```c
float4 f = (float4) (1.0f, 2.0f, 3.0f, 4.0f);
float2 low, high;
float2 o, e;

low = f.lo;     // returns f.xy (1.0f, 2.0f)
high = f.hi;    // returns f.zw (3.0f, 4.0f)
o = f.odd;      // returns f.yw (2.0f, 4.0f)
e = f.even;     // returns f.xz (1.0f, 3.0f)
```
OpenCL™ Program Flow

- OpenGL Shader Programs
- OpenGL Buffers
- CUDA Streams

Context

- Programs
- Kernels
- Memory Objects
- Command Queue

Compile
Create data & arguments
Send to execution
OpenCL API

- Walkthrough OpenCL *host* code for running *vecAdd* kernel:

```c
__kernel void vecAdd(__global const float *a, __global const float *b, __global float *c)
{
    int i = get_global_id(0);
    c[i] = a[i] + b[i];
}
```

OpenCL API

// create OpenCL device & context
cl_context hContext;
hContext = clCreateContextFromType(0,
    CL_DEVICE_TYPE_TYPE_GPU, 0, 0, 0);
OpenCL API

// create OpenCL device & context
cl_context hContext;
hContext = clCreateContextFromType(0,
CL_DEVICE_TYPE_GPU, 0, 0, 0);

Create a context for a GPU
OpenCL API

// query all devices available to the context
size_t nContextDescriptorSize;
clGetContextInfo(hContext, CL_CONTEXT_DEVICES, 0, 0, &nContextDescriptorSize);
cl_device_id aDevices = malloc(nContextDescriptorSize);
clGetContextInfo(hContext, CL_CONTEXT_DEVICES, nContextDescriptorSize, aDevices, 0);
OpenCL API

// query all devices available to the context
size_t nContextDescriptorSize;
clGetContextInfo(hContext, CL_CONTEXT_DEVICES,
0, 0, &nContextDescriptorSize);
cl_device_id aDevices =
malloc(nContextDescriptorSize);
clGetContextInfo(hContext, CL_CONTEXT_DEVICES,
nContextDescriptorSize, aDevices, 0);

Retrieve an array of each GPU
Choosing Devices

• A system may have several devices - which is best?
• The “best” device is algorithm-dependent
• Query device info with: `clGetDeviceInfo(device, param_name, *value)`
  – Number of compute units: `CL_DEVICE_MAX_COMPUTE_UNITS`
  – Clock frequency: `CL_DEVICE_CLOCK_FREQUENCY`
  – Memory size: `CL_DEVICE_GLOBAL_MEM_SIZE`
  – Extensions (double precision, atomics, etc.)
• Pick best device for your algorithm
OpenCL API

// create a command queue for first
// device the context reported
cl_command_queue hCmdQueue;

hCmdQueue =
    clCreateCommandQueue(hContext,
aDevices[0], 0, 0);
OpenCL API

// create a command queue for first
// device the context reported
cl_command_queue hCmdQueue;

Create a command queue (CUDA stream) for the first GPU

hCmdQueue =
clCreateCommandQueue(hContext,
aDevices[0], 0, 0);
OpenCL API

// create & compile program
cl_program hProgram;

hProgram =
    clCreateProgramWithSource(hContext, 1, source, 0, 0);
clBuildProgram(hProgram, 0, 0, 0, 0, 0);

• A program contains one or more kernels. Think dll.
• Provide kernel source as a string
• Can also compile offline
OpenCL API

// create kernel
cl_kernel hKernel;
hKernel = clCreateKernel(hProgram, "vecAdd", 0);

Create kernel from program
Program and Kernel Objects

• Program objects encapsulate:
  – a program source or binary
  – list of devices and latest successfully built executable for each device
  – a list of kernel objects

• Kernel objects encapsulate:
  – a specific kernel function in a program - declared with the kernel qualifier
  – argument values
  – kernel objects created after the program executable has been built
// allocate host vectors
float* pA = new float[cnDimension];
float* pB = new float[cnDimension];
float* pC = new float[cnDimension];

// initialize host memory
randomInit(pA, cnDimension);
randomInit(pB, cnDimension);
OpenCL API

```c
cl_mem hDeviceMemA = clCreateBuffer(
    hContext,
    CL_MEM_READ_ONLY | CL_MEM_COPY_HOST_PTR,  // CL_MEM_READ_ONLY
    cnDimension * sizeof(cl_float),
    pA, 0);

cl_mem hDeviceMemB = /* ... */
```
OpenCL API

```c
cl_mem hDeviceMemA = clCreateBuffer(
    hContext,
    CL_MEM_READ_ONLY | CL_MEM_COPY_HOST_PTR,
    cnDimension * sizeof(cl_float),
    pA, 0);

cl_mem hDeviceMemB = /* ... */
```

Create buffers for kernel input. Read only in the kernel. Written by the host.
hDeviceMemC = clCreateBuffer(hContext,
  CL_MEM_WRITE_ONLY,
  cnDimension * sizeof(cl_float),
  0, 0);

Create buffer for kernel output.
OpenCL API

// setup parameter values
clSetKernelArg(hKernel, 0, sizeof(cl_mem), (void *) &hDeviceMemA);
clSetKernelArg(hKernel, 1, sizeof(cl_mem), (void *) &hDeviceMemB);
clSetKernelArg(hKernel, 2, sizeof(cl_mem), (void *) &hDeviceMemC);
OpenCL API

// execute kernel
clEnqueueNDRangeKernel(hCmdQueue,
    hKernel, 1, 0, &cnDimension, 0, 0, 0, 0);

// copy results from device back to host
clEnqueueReadBuffer(hContext,
    hDeviceMemC, CL_TRUE, 0,
    cnDimension * sizeof(cl_float),
    pC, 0, 0, 0);
OpenCL API

// execute kernel
clEnqueueNDRangeKernel(hCmdQueue,
    hKernel, 1, 0, &cnDimension, 0, 0, 0, 0);

// copy results from device back to host
clEnqueueReadBuffer(hContext,
    hDeviceMemC, CL_TRUE, 0,
    cnDimension * sizeof(cl_float),
    pC, 0, 0, 0);

Let OpenCL pick work group size

Blocking read
clEnqueueNDRangeKernel

cl_int clEnqueueNDRangeKernel (  
    cl_command_queue command_queue,  
    cl_kernel kernel,  
    cl_uint work_dim, <=3  
    const size_t *global_work_offset, NULL  
    const size_t *global_work_size,  
    const size_t *local_work_size,  
    cl_uint num_events_in_wait_list,  
    const cl_event *event_wait_list,  
    cl_event *event)

global_work_size must be divisible by local_work_size
OpenCL API

delete [] pA;
delete [] pB;
delete [] pC;
clReleaseMemObj(hDeviceMemA);
clReleaseMemObj(hDeviceMemB);
clReleaseMemObj(hDeviceMemC);
CUDA Pointer Traversal

struct Node { Node* next; }

n = n->next; // undefined operation in OpenCL, // since ‘n’ here is a kernel input
OpenCL Pointer Traversal

struct Node { unsigned int next; }
...
  n = bufBase + n; // pointer arithmetic is fine, bufBase is
  // a kernel input param to the buffer’s beginning
Intro OpenCL Tutorial

Benedict R. Gaster, AMD Architect, OpenCL™
The “Hello World” program in OpenCL

• Programs are passed to the OpenCL runtime via API calls expecting values of type char *

• Often, it is convenient to keep these programs in separate source files
  – For this tutorial, device programs are stored in files with names of the form name_kernels.cl
  – The corresponding device programs are loaded at runtime and passed to the OpenCL API
#include <utility>
#define __NO_STD_VECTOR
// Use cl::vector instead of STL version
#include <CL/cl.hpp>

// additional C++ headers, which are agnostic to // OpenCL.
#include <cstdio>
#include <cstdlib>
#include <fstream>
#include <iostream>
#include <string>
#include <iterator>

const std::string hw("Hello World\n");
inline void checkErr(cl_int err, const char * name)
{
    if (err != CL_SUCCESS) {
        std::cerr << "ERROR: " << name
                  << " (" << err << ")" << std::endl;
        exit(EXIT_FAILURE);
    }
}
int main(void)
{
    cl_int err;
    cl::vector< cl::Platform > platformList;
    cl::Platform::get(&platformList);
    checkErr(platformList.size() != 0 ? CL_SUCCESS : -1, "cl::Platform::get");
    std::cerr << "Platform number is: " << platformList.size() << std::endl;

    std::string platformVendor;
    platformList[0].getInfo((cl_platform_info)CL_PLATFORM_VENDOR, &platformVendor);
    std::cerr << "Platform is by: " "n";
OpenCL Contexts

```cpp
cl_context_properties cprops[3] =
    {
        CL_CONTEXT_PLATFORM,
        (cl_context_properties)(platformList[0])(),
        0
    };

cl::Context context(
    CL_DEVICE_TYPE_CPU,
    cprops,
    NULL,
    NULL,
    NULL,
    &err);
checkErr(err, "Context::Context()" );
```

*Just pick first platform*
char * outH = new char[hw.length()+1];
cl::Buffer outCL(
    context,
    CL_MEM_WRITE_ONLY | CL_MEM_USE_HOST_PTR,
    hw.length()+1,
    outH,
    &err);
checkErr(err, "Buffer::Buffer()");
OpenCL Devices

```
cl::vector<cl::Device> devices;
devices = context.getInfo<CL_CONTEXT_DEVICES>();
checkErr(devices.size() > 0 ? CL_SUCCESS : -1, "devices.size() > 0");
```

In OpenCL many operations are performed with respect to a given context. For example, buffers (1D regions of memory) and images (2D and 3D regions of memory) allocation are all context operations. But there are also device specific operations. For example, program compilation and kernel execution are on a per device basis, and for these a specific device handle is required.
std::ifstream file("lesson1_kernels.cl");
checkErr(file.is_open() ? CL_SUCCESS:-1, "lesson1_kernel.cl");
std::string
    prog(std::istreambuf_iterator<char>(file),
         (std::istreambuf_iterator<char>()));
cl::Program::Sources source(1,
    std::make_pair(prog.c_str(), prog.length()+1));
cl::Program program(context, source);
err = program.build(devices,"");
checkErr(err, "Program::build()");
Kernel Objects

```cpp
cl::Kernel kernel(program, "hello", &err);
checkErr(err, "Kernel::Kernel()" );
err = kernel.setArg(0, outCL);
checkErr(err, "Kernel::setArg()" );
```
Launching the Kernel

c:::CommandQueue queue(context, devices[0], 0, 
           &err);
checkErr(err, "CommandQueue::CommandQueue()"); 
c:::Event event;
err = queue.enqueueNDRangeKernel( 
    kernel, 
    c:::NullRange, 
    c:::NDRange(hw.length()+1),
    c:::NDRange(1, 1),
    NULL, 
    &event);
checkErr(err, 
    "ComamndQueue::enqueueNDRangeKernel()");
event.wait();
err = queue.enqueueReadBuffer(
    outCL,
    CL_TRUE,
    0,
    hw.length()+1,
    outH);
checkErr(err,
    "ComamndQueue::enqueueReadBuffer()"");
std::cout << outH;
return EXIT_SUCCESS;
}
#pragma OPENCL EXTENSION cl_khr_byte_addressable_store : enable

__constant char hw[] = "Hello World\n";
__kernel void hello(__global char * out)
{
    size_t tid = get_global_id(0);
    out[tid] = hw[tid];
}