

# A Decentralized Key Management Scheme via Neighborhood Prediction in Mobile Wireless Networks

Xiuyuan Zheng<sup>1</sup>, Hui Wang<sup>2</sup>, Yingying Chen<sup>1</sup>, Hongbo Liu<sup>1</sup>, Ruilin Liu<sup>2</sup>

Department of ECE<sup>1</sup>, Department of CS<sup>2</sup>

Stevens Institute of Technology, Hoboken, NJ

Email: {xzheng1, yingying.chen, hliu3}@stevens.edu<sup>1</sup>, {hwang, rliu3}@cs.stevens.edu<sup>2</sup>

**Abstract**—The wireless data collected in mobile environments provides tremendous opportunities to build new applications in various domains such as Vehicular Ad Hoc Networks and mobile social networks. One of the biggest challenges is how to store these data. Storing the data decentralized in wireless devices is an attractive approach because of its major advantages over centralized ones. In this work, to facilitate effective access control of the wireless data in distributed data storage, we propose a fully decentralized key management scheme by utilizing a cryptography-based secret sharing method. The secret sharing method splits the keys into multiple shares and distributes them to multiple nodes, which brings the challenge that due to node mobility, these key shares may not be available in the neighborhood when they are needed for key reconstruction. To address this challenge arising from mobile environments, we propose the Transitive Prediction (TRAP) protocol that distributes key shares among devices that are traveling together. We derive a theoretical analysis of the robustness of our approach. Furthermore, inside TRAP, we develop three key distribution schemes that utilize the correlation relationship embedded among devices that are traveling together. Our key distribution schemes maximize the chance of successful key reconstruction and minimize the communication overhead. Our extensive simulation results demonstrate that our key distribution schemes are highly effective, and thus provide strong evidence of the feasibility of applying our approach to support distributed data storage in wireless networks.

## I. INTRODUCTION

The rapid advancement of wireless technologies has led to a future where wireless networks will be pervasively deployed. As a matter of fact, with the increasing programmability of wireless devices and the continuously reducing cost of communication radios, mobile wireless networks are becoming a part of our social life. For instance, vehicles are equipped with wireless communication devices to form Vehicular Ad Hoc Networks (VANETs), in which vehicles have the sensing capability to collect data regarding to road conditions and traffic scenarios [22]. Another example is that data collection and real-time multimedia blogs [3], [14] enabled by various sensing capabilities on mobile phones, such as cameras, GPS, and accelerometers, provide geo-related information that supports effective mobile social collaboration. Thus, the wireless data collected in the

mobile environments provide abundant information to build pervasive applications in our social life.

Most of the existing work [20] requires the data to be sent back to centralized storage nodes continuously and only considers stable network topology. However, this may incur high communication overhead and excessive energy consumption among wireless devices by continuously forwarding the data to storage nodes. To address these issues, distributed data storage [8], [9], [16], [19], [20] in wireless networks has attracted much attention. The distributed data storage has major advantages over centralized approaches: storing the data on the collected wireless device or in-network storage nodes decreases the need of constant data forwarding back to centralized places, which largely reduces the communication in the network and the energy consumption on individual devices, and consequently eliminates the existence of centralized storage and enables efficient and resilient data access. Furthermore, as wireless networks become more pervasive, new-generation wireless devices with significant memory and powerful processing capabilities are available (i.e., smart phone and laptops), making the deployment of distributed data storage not only feasible but also practical. In this work, the collected data will be stored in each *collector node*, i.e., the mobile device that collects the data.

In many cases, the data collected by mobile wireless networks contain sensitive information. For instance, an adversary can derive the trajectories of vehicular drivers to infer their social behaviors, or analyze the video clips embedded in the multimedia blogs to derive users' lifestyles. Such vulnerabilities are significantly threatening the deployment of applications that utilize the large-scale data sets collected by wireless mobile networks. Therefore, while the wireless data provides abundant opportunities for developing new applications, it could also be dangerous if not handled appropriately and misused by adversaries. Thus, secure data storage must be achieved before widespread adoption of distributed data storage. One of the main challenges in utilizing the distributed wireless data is to develop effective mechanisms that control the access of data so

that the right information is shared with the right party at the right time.

Traditional encryption-based access control approaches employ an individual or a group of centralized certification authorities for key management [1], [25]. However, it is hard to scale with the increasing size and the mobility of devices in wireless networks and can become a single point of failure. In this paper, we propose a *fully decentralized* key management framework by utilizing the cryptography-based secret sharing method. The secret sharing approach has been very useful in developing decentralized security protocols [13], [10]. In our decentralized framework, the data is encrypted and the decryption key is divided and shared among mobile devices in the network. However, the mobility of devices introduces environmental dynamics and makes it hard to reconstruct the key. To cope with mobility, we propose to distribute the key shares among devices that are traveling together with the collector node through neighborhood prediction. Indeed, in our daily life, people are usually travelling together to common destinations or areas, e.g., commuting along the same train lines or visiting a museum together. This co-movement phenomenon makes our neighborhood prediction feasible. We further develop the *Transitive Prediction (TRAP)* protocol that helps to maximize the chances of successful key share reconstruction and minimize the communication overhead, and in the meanwhile avoiding the degradation of the security guarantee of data access.

Inside *TRAP*, we design three key distribution schemes. These three key distribution schemes can be classified into two categories, the one that does not respect the relationships between moving patterns of different devices, and the one that does. For the first type, we develop a scheme named *random selection*, while for the second type, we develop two schemes, namely *association-probability-based*, and *association-rule-based*. Furthermore, we derive a theoretical analysis of the robustness of our mechanism.

To evaluate the effectiveness and efficiency of our approach, we conducted simulations by using simulated mobile wireless networks in a city environment [7] with different moving speeds: walking speed and vehicular traveling speed. Our results show that our key distribution schemes are highly effective to achieve successful key reconstruction in mobile and decentralized environments, and thus providing strong evidence of the feasibility of applying our decentralized key management scheme in mobile wireless networks.

The remainder of the paper is organized as follows. We first put our work into the broader context of the current research in Section II. We then present our decentralized key management framework for mobile wireless networks in Section III. The robustness analysis of our approach is provided in Section IV. In Section V, we describe our key distribution schemes for efficient

key reconstruction. Section VI presents our simulation methodology and results using various data sets generated from simulated mobile wireless networks. Finally, we conclude our work in Section VII.

## II. RELATED WORK

Key management is a key component of encryption-based access control system. Recent work has been focused on eliminating the need of centralized authentication management in wireless networks. In particular, to address mobility, [4], [23] made use of privileged side channels when mobile users are in the vicinity of each other. The secure side channel is used to set up security associations between nodes by exchanging cryptographic materials. However, the availability of the privileged side channels is not guaranteed.

On the other hand, the secret sharing method has been actively studied in the field of cryptography [18], [25], [21]. The advantage of using the secret sharing method is that the possibility of a single point of failure is significantly reduced. Moreover, the secret sharing method has been applied in mobile ad hoc networks [25], [13], [10]. [25] proposed a distributed public-key management scheme based on threshold secret sharing in which the CA services are divided into a certain number of specialized servers. The drawback is that it assumes some nodes must behave as servers. When moving towards fully distributed infrastructure, a decentralized authentication protocol is developed to distribute the authentication of a certificate authority (CA) by utilizing secret sharing [13]. However, it did not consider the mobility of nodes, and thus making it inapplicable to mobile environments.

The work that is most closely related to ours is [10]. By taking into the consideration of mobility, [10] introduced a redundancy-based key distribution scheme in secret sharing to achieve a decentralized CA. Basically, more than one key share are distributed to each node in order to increase the probability of successful key reconstruction in mobile networks. However, the security level of the system can be degraded due to having multiple redundant key shares on nodes. Our work is novel in that our proposed decentralized key management framework employing secret sharing maintains the security guarantee of the data access through neighborhood prediction and distributes key shares only to those nodes that are traveling together.

## III. DECENTRALIZED KEY MANAGEMENT FRAMEWORK

We present the framework of our decentralized key management approach in this section. We first discuss the network model. We then present our approach of decentralized key management. Finally, we describe the adversary model.

### A. Network model

We consider mobile wireless networks, which contain a large number of wireless devices (e.g., mobile phones or on board sensing units on vehicles). Each device has a unique ID and may perform different functionalities in the network. Devices may freely roam in the network, and the number of nodes in a network may be dynamically changing due to its capability of mobility, i.e., mobile nodes may join, leave, or fail over time. Devising a generic approach that works across all varieties of mobile wireless networks is impractical. Therefore, as a starting point, we target our solutions to a category of mobile wireless networks with the following characteristics.

**Mobility.** Each node is moving in some patterns, or just randomly, in a large well-defined area, though the nodes are not aware of their moving patterns, if there is any. There are no pre-defined trajectories for each node. However, we assume there exists a *co-movement* pattern within nodes, i.e., group of nodes may travel together to common destinations. For example, a group of tourists in New York City may travel to visit the Metropolitan Museum together and each of them can use their mobile phones to take pictures, shoot videos, and write multimedia blogs on the way.

**Neighbor-Aware.** Each node has a communication range and can communicate only with nodes within its transmission range. We call the nodes in the transmission range the *neighbors*. Mobility of nodes may result in the change of the neighborhood. However, we assume that for every node, it has a comparatively stable neighborhood within a period of time.

**Location-Aware.** Each node knows their physical locations at all time points during moving. This is a reasonable assumption as most of wireless devices (e.g., mobile phones or vehicles) are equipped with GPS or some other approximate but less burdensome localization algorithms [12]. In many cases the location of the collected data is important. For example, knowing that a traffic accident occurred, which requires to inform the neighboring nodes, but without knowing where it occurred is useless.

**Distributed Data Storage.** Each node stores the data it has collected. The data will be stored within the network at each collector node (e.g., mobile phones or vehicles) unless it is required to be sent to a centralized storage space for backup. By uploading data in a lazy fashion (i.e., on-demand only), distributed data storage enables real-time query evaluation and avoids frequent data transfer from the wireless devices to the centralized storage, and consequently reduces battery power consumption and decreases the communication overhead of the network.

### B. Distributed Key Management Model

1) *Node Authentication:* There has been sufficient work [25], [13], [10] that we can employ to perform

node authentication. [25] proposed a partially distributed certificate authority scheme that supports authority services to be shared by multiple servers. [13] proposed a distributed cryptography-based authentication solution that distributes a certificate key to each node. [10] extended [13] by providing a redundancy-based solution for node authentication. Thus, we can adopt these existing works for node authentication in our network and mainly focus on studying decentralized key management for secure data access. In our work, whenever a node enters the network, it has to pass the authentication procedure. When a node in the network tries to access data, the node needs to collect  $m$  key pieces. Thus, an attacker node has to compromise up to  $m$  nodes, which means that it has to succeed for  $m$  trials to hack the system with complex overhead. This highly increases the security level of our system compared with the system that uses a centralized authority for data access, so that the attacker node only has to hack one node, that is, the centralized authority node.

2) *Secret Sharing Based Key Management:* To prevent the misuse of the data and protect the privacy of mobile users, the data is encrypted in our framework. Further, we propose to use the secret sharing scheme to achieve decentralized key management in dynamic wireless environments.

Secret sharing, also named threshold secret sharing, is originated from [18]. Specifically, in a  $(m, n)$  secret sharing scheme, a secret is distributed among  $n$  participants; only by collecting  $m$  ( $m \leq n$ ) secret shares can re-construct the secret. The decision of values for  $m$  and  $n$  controls the strength of the system.

**Key Distribution.** More formally, in mobile wireless networks, a data decryption key  $S$  is shared among  $n$  devices. To share the  $S$  among the  $n$  devices,  $\{c_1, c_2, \dots, c_n\}$ , we pick a polynomial of order  $m - 1$ :  $f(x) = S + a_1x + a_2x^2 + \dots + a_{m-1}x^{m-1}$ . Then the key share  $S_i$  to be distributed to device  $i$  is  $S_i = f(c_i) \bmod p$ , where  $p$  is a big prime number, and  $c_i$  denotes the  $i$ th device among  $n$ .

We develop the secret sharing method in a fully distributed manner: Each collector node acts as the dealer node as defined in the secret sharing scheme [18] and is responsible to distribute the decryption key of its own data. Furthermore, since each collector node can encrypt its data at different time periods, there can be multiple keys associated with each node in our network. Thus, in order to identify the key shares that belong to the same key, the collector node will generate a unique key ID to append to each key share. The unique key ID will help to identify the key shares that belong to the same decryption key. The collector node will destruct the decryption key after it distributed the key shares.

**Key Reconstruction.** At a later time, the secret key  $S$  can be reconstructed by using Lagrange interpolation  $S = f(0) = \sum_{i=1}^m S_{c_i} * l_{c_i}(x) \pmod p$ , where  $p$  is a big

prime number, and  $l_{c_i}(x)$  is the lagrange coefficient of the  $i$ th device and is defined as  $l_{c_i}(x) = \prod_{j=1, j \neq i}^m \frac{x - c_j}{c_j - c_i}$ . Any subsets of  $m$  key shares could reconstruct the decryption key and each wireless device is unaware of others' shares. Further, only the authorized node by the authentication protocol, e.g., [13], which owns the certificate key, can reconstruct secret key  $S$ .

**Key Updating.** Given sufficiently long time, an adversary could compromise  $m$  nodes and reconstruct the decryption key of the data. To make our secret sharing based key management more robust, the key shares will be updated periodically. We apply proactive secret sharing [21] in which the key shares will be expired after a specified time period controlled by the collector node. The collector node will re-distribute a set of key shares once the key shares in the previous distribution have expired. The new key share  $f_{new}(x)$  can be generated as  $f_{new}(x) = S + (a_1 + b_1)x + \dots + (a_{m-1} + b_{m-1})x^{m-1} \pmod{p}$ . Periodically, the collector node will distribute the  $n$  newly generated key shares to  $n$  wireless devices. The old keys are expired and thus are discarded.

### 3) Handling Mobility via Neighborhood Prediction:

In a mobile wireless network, the devices carrying key shares may move farther away, causing much communication overhead during key reconstruction and even reconstruction failure (e.g., unreachable devices). Thus, it is desirable to distribute key shares to devices that are moving together with the collector node, and consequently increasing the success rate of key reconstruction in dynamic network environments and reducing the communication overhead and energy consumption during the reconstruction process. However, this brings in a new challenge of how to determine the devices that are traveling together with the collector node. To address this issue, we propose to use neighborhood prediction. In particular, we developed an array of key distribution schemes, which explore correlations embedded in the moving patterns of wireless devices, to predict devices that are traveling together for efficient key distribution. The detailed schemes will be presented in Section V. During the key distribution phase, the collector node utilizes these schemes to pick the top  $n$  wireless devices that are most likely traveling together with it, and distributes the  $n$  key shares to these devices.

Further, as stated in our network model each mobile wireless device only keeps the information of its 1-hop neighbors (i.e., devices within its transmission range). During the key distribution phase, it is possible that there are not enough devices within the 1-hop range to share the key, i.e., the devices within the 1-hop range of the collector node are less than  $n$ . To address this problem, there are two possible solutions:

*Solution 1:* The collector could request its 1-hop neighbors to send the information of their respective 1-hop neighbors back to it as candidates. Under the

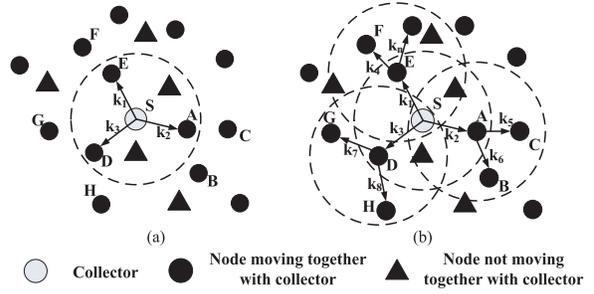


Figure 1. Illustration of TRAP in a 2-hop scenario

scenario that the returned number of candidates is still less than  $n$ , the collector will make iterative requests to the neighbors of neighbors to collect more candidate devices, until it collects at least  $n$  candidates. Then it will run the key distribution scheme on these candidates and choose the top  $n$  devices from the results as the key share holders.

*Solution 2:* The idea behind the second solution is that the co-movement is *transitive* in practice. For instance, if a mobile user  $A$  is traveling together with user  $B$ , meanwhile  $B$  is traveling together with  $C$ , it is highly likely that  $A$  is also traveling together with  $C$ . Thus, the collector node can utilize this property and distribute the prediction responsibility of key distribution to its neighbors for further prediction of the devices traveling together when there are less than  $n$  devices within the 1-hop neighborhood for key share distribution. The prediction of key distribution (i.e., the key distribution scheme) can be successively invoked by the neighbors of the neighbors until enough candidates are found. The predicted results at each neighboring node during each round of invocation will be sent back to the collector node as candidates for choosing the top  $n$  devices.

**Transitive Prediction (TRAP) Protocol.** We note that Solution 1 may incur high computational cost and expensive energy consumption at the collector node. Thus, in this work, we take Solution 2 and develop a fully distributed prediction protocol called *Transitive Prediction (TRAP)* that builds on top of our key distribution schemes. We utilize a layered approach (i.e., we call 1-hop neighbors of a node as one layer) to successively find enough devices that are traveling together with the collector node for resilient key distribution in multi-hop mobile environments. In *TRAP*, the  $k$ -hop neighbors of the collector node is defined as the 1-hop neighbors of the  $(k - 1)$ -hop neighbors of the collector node with  $k > 1$ . Figure 1 depicts TRAP of finding  $n$  traveling together devices with the collector node in a 2-hop scenario for key distribution.

At every round of TRAP, each involved neighboring node will run the key distribution scheme to predict top  $x$  devices from its 1-hop neighbors and send the prediction results as candidates back to the collector node. To ensure returning the sufficient number of candidates, we

choose  $x = n$  in TRAP. The collector node will then choose the top  $n$  devices from the returned candidates based on the prediction criteria (e.g., the association rule in *Association-rule-based* scheme in Section V) in our key distribution schemes to share the key. Thus, in TRAP the computation of successive prediction is distributed at the neighbors that are traveling together, and consequently the computational cost and energy consumption at the collector nodes is significantly reduced.

### C. Adversary Model

In this work, we consider adversaries that can compromise any wireless devices to obtain the key shares. Once a node is compromised, an adversary can get the key share stored on the node if any, however, it cannot decrypt the data stored on the compromised node. An adversary needs to compromise up to  $m$  nodes in order to reconstruct the key to decrypt the data on a collector node. Further, once a node is compromised, an adversary may generate fake data and then distribute key shares of the fake data in the network. However, this behavior will not affect the secure access of the legitimate data cached in the network. Thus, it is not the focus of our work.

## IV. ROBUSTNESS ANALYSIS

In this section, we formally analyze the robustness of our TRAP protocol in mobile wireless networks. For mathematical tractability, we make the assumption that the wireless nodes are randomly deployed in the network, the node distribution follows a homogeneous Poisson point process with a density of  $\rho$  nodes per unit area [5], [17]. Note that  $\rho$  varies over the entire large network due to the mobility of nodes. This assumption is reasonable and has been widely used in analyzing multi-hop mobile wireless networks [6], [15], [11].

### A. Robustness Analysis

The  $(m, n)$  secret sharing scheme splits the decryption key into  $n$  shares and distributes the  $n$  shares to  $n$  devices. However, due to the mobility of the network, it is possible that these key shares may not be accompanied together while time goes. Thus in the following, we analyze the robustness of the protocol via the probability that legitimate users can successfully reconstruct the key.

**One-hop scenario.** This scenario considers the case that there are sufficient  $m$  key shares available in the 1-hop neighborhood of the node for key re-construction. Assume that each node has a transmission range  $r$ ; thus it covers an area  $A = \pi r^2$ . Since the number of nodes  $N$  in the area A follows a Poisson distribution, the probability that a node has  $i$  nodes in its 1-hop neighborhood is  $Pr(N = i) = \frac{\gamma^i}{i!} e^{-\gamma}$ , where the expected node degree  $\gamma = \rho \pi r^2$ . Further, we define  $p_1$ , the percentage of nodes in the 1-hop neighborhood of the collector node that hold key shares. Let  $i_1$  be the total number of nodes in 1-hop neighborhood. Since as each legitimate

user possesses a key share already, it needs to collect another  $m - 1$  key shares to reconstruct the key. It is straightforward that  $p_1 i_1$  must be at least  $m - 1$ . Thus we have:

$$\begin{aligned} Pr(i_1 p_1 \geq m - 1) &= 1 - Pr(i_1 < \frac{m - 1}{p_1}) \\ &= 1 - \sum_{j=1}^{\lfloor \frac{m-1}{p_1} \rfloor - 1} \frac{\gamma^j}{j!} e^{-\gamma}, \end{aligned} \quad (1)$$

where  $\gamma = \rho \pi r^2$ .

**Multi-hop scenario.** This scenario considers the case that there are less than  $m - 1$  key shares available in the  $(k - 1)$ -hop ( $k \geq 2$ ) neighborhood, but at least  $m - 1$  key shares in the  $k$ -hop neighborhood of the collector node for key re-construction. The  $(k - 1)$ -hop neighborhood covers an area  $A_{k-1} = \pi((k - 1)r)^2$ , while the  $k$ -hop neighborhood of a node (with transmission range  $r$ ) covers an area  $A_k = \pi(kr)^2$ . Let  $i_{k-1}$  and  $i_k$  be the number of neighbors in the  $(k - 1)$ -hop and  $k$ -hop neighborhood. Similar to the 1-hop scenario, we define  $p_k$  as the percentage of nodes in  $k$ -hop neighborhood that carry key shares. Since the legitimate user (holding a key share already) can collect  $t \in [m - 1, n - 1]$  key shares from the  $k$ -hop neighborhood but less than  $m - 1$  neighbors from the  $(k - 1)$ -hop neighborhood, we have:

$$\begin{aligned} &Pr(m - 1 \leq i_k p_k \leq n - 1 | i_{k-1} p_{k-1} < m - 1) \\ &= \frac{Pr(\frac{m-1}{p_k} \leq i_k \leq \frac{n-1}{p_k}) + Pr(i_{k-1} < \frac{m-1}{p_{k-1}})}{Pr(i_{k-1} < \frac{m-1}{p_{k-1}})} \\ &- \frac{Pr(\frac{m-1}{p_k} \leq i_k \leq \frac{n-1}{p_k} \cup i_{k-1} < \frac{m-1}{p_{k-1}})}{Pr(i_{k-1} < \frac{m-1}{p_{k-1}})} \\ &= 1 - \frac{Pr(i_k < \frac{m-1}{p_k})}{Pr(i_{k-1} < \frac{m-1}{p_{k-1}})} \\ &= 1 - \frac{\sum_{j=1}^{\lfloor \frac{m-1}{p_k} \rfloor - 1} \frac{\gamma^j}{j!} e^{-\gamma}}{\sum_{j=1}^{\lfloor \frac{m-1}{p_{k-1}} \rfloor - 1} \frac{\gamma'^j}{j!} e^{-\gamma'}}, \end{aligned} \quad (2)$$

where the expected node degree  $\gamma' = \rho \pi (k - 1)^2 r^2$  and  $\gamma = \rho \pi k^2 r^2$ .

### B. Discussion

Based on the theoretical analysis, we choose different parameter setup to measure the probability of robustness in our approach.

We fix the value of  $\gamma$  (e.g.,  $\gamma = 15$ ), the expected number of nodes in 1-hop neighborhood, and vary the value of  $p_1$ , the ratio of the nodes in the 1-hop neighborhood that holds key shares. Figure 2 (a) presents the robustness probability of key reconstruction in the 1-hop neighborhood with  $n = 15$  and  $m = 4, 6, 8$  and 10 for the setup of the  $(m, n)$  secret sharing scheme. We observed that for all the  $m$  values, the robustness probability increases

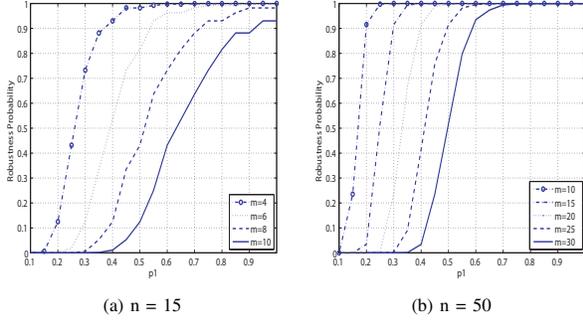


Figure 2. Robustness probability for 1-hop scenario with (a)  $m = 4, 6, 8,$  and  $10$  and (b)  $m = 10, 15, 20, 25,$  and  $30$  in the secret sharing method.

with increasing  $p_1$ . This is straightforward as the more key shares moving together, they make better chance for key reconstruction. Figure 2(b) shows the results when we change to  $n = 50$  and  $m = 10, 15, 20, 25$  and  $30$  for the setup of the  $(m, n)$  secret sharing scheme. It has a similar trend as Figure 2(a). Furthermore, we observed that the smaller  $m$  value is, the smaller  $p_1$  is needed to achieve a robustness probability threshold, since fewer number of key shares are needed for key reconstruction.

Figure 3 presents the robustness probability in a 2-hop scenario with the  $(10, 15)$  secret sharing method. Similar to the 1-hop neighborhood scenario, we vary the value of  $p_2$ , the ratio of the nodes holding key shares in the 2-hop neighborhood. Meanwhile, we set the value of  $p_1$ , the percentage of nodes holding key shares in the 1-hop neighborhood, as  $0.1, 0.3$  and  $0.5$  respectively. In general, the analytical robustness probability is as high as near to 1 for most of the cases. This indicates the feasibility of applying TRAP using the secret sharing method to mobile wireless networks.

We note that the value of  $m$  and  $n$  are both adjustable in our scheme depending on the scheme designer, which can vary from the network size, robustness requirement, security level and other considerations. The security analysis of our approach can be found in [24].

## V. KEY DISTRIBUTION SCHEMES

Careless key distribution will result in key shares scattered across the whole network and thus degrade the performance of key reconstruction. Therefore, how the key shares are distributed is of utmost importance. Based on our theoretical analysis in Section IV, ideally the key shares should be distributed to the nodes that move together in the network. In this section, we investigate three schemes to decide which nodes should be assigned the key shares in the TRAP protocol. The three key distribution schemes can be classified into two types, the one that does not respect the relationships between moving patterns of different nodes (i.e., correlation-blind scheme), and the one that does (i.e., correlation-aware schemes). For the first type, we design a scheme named *random selection*, while for the second type, we design two schemes, namely *association-probability-based*, and

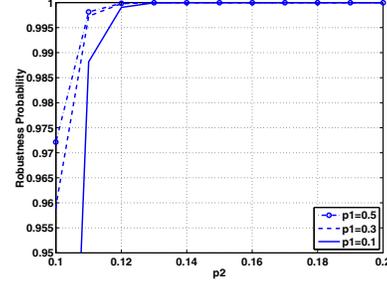


Figure 3. Robustness Probability in the 2-hop scenario with  $(10, 15)$  secret sharing setup.

*association-rule-based*. As it is possible that there are less than  $n$  nodes in the 1-hop neighborhood of the current node, these schemes aim at choosing  $x \leq n$  nodes, where  $x$  is either the number of available nodes in the current 1-hop neighborhood (when there are less than  $n$  such nodes), or  $n$ , when there are sufficient  $n$  nodes in the 1-hop neighborhood.

### A. Correlation-blind Scheme

We design the *random selection* scheme that picks  $x$  nodes without considering the moving patterns of these nodes. The idea is straightforward: the  $x$  nodes are randomly picked from the 1-hop neighborhood, without taking the moving patterns of these nodes into consideration. This is a naive approach to distribute the key shares. It is obvious that this scheme may be suffered from inefficient key reconstruction, as the  $x$  nodes that hold key shares are likely to move apart in the future and consequently the collection of  $x$  key shares from these  $x$  nodes will be costly in terms of communication overhead. Unfortunately, most existing schemes [18], [25], [13] use this random-selection strategy to do the key distribution.

### B. Correlation-aware Schemes

The key to improve the performance of key reconstruction procedure is to distribute the key shares to the nodes that are moving together, i.e., the nodes that have strong correlations between their moving trajectories. To achieve this goal, we design two schemes, namely *association-probability-based*, and *association-rule-based*, to determine the  $x$  nodes for key distribution by considering the correlations between their moving patterns. For these two schemes, we use different mechanisms to measure the correlations/associations between different moving trajectories.

1) *Association-probability-based Scheme*: In this scheme, we measure the correlation/association between different moving trajectories as probability. In particular, given a current node  $c$  and a candidate node  $c'$ , let  $T$  and  $T'$  be the trajectories of  $c$  and  $c'$  within the time window  $W$ , then the association probability  $Pr_a$  between  $c$  and  $c'$  is computed as  $Pr_a = C/|W|$ , where  $C$  is the number of time points in  $W$  that  $c'$  is in the 1-hop neighborhood

Time Point	Neighbor ID
$T_1$	$c_1, c_3, c_4$
$T_2$	$c_2, c_3, c_5$
$T_3$	$c_1, c_2, c_3, c_5$
$T_4$	$c_1, c_2, c_5$

(a) The neighborhood of  $c_0$

Neighbor Set	Support
$\{c_1, c_2, c_3\}$	0.25
$\{c_1, c_2, c_5\}$	0.5
$\{c_2, c_3, c_5\}$	0.5
$\{c_1, c_3, c_5\}$	0.25

(c) The support of 3-node set

Neighbor Set	Support
$\{c_1\}$	0.75
$\{c_2\}$	0.75
$\{c_3\}$	0.75
$\{c_4\}$	0.25
$\{c_5\}$	0.75

(b) The support of 1-node set

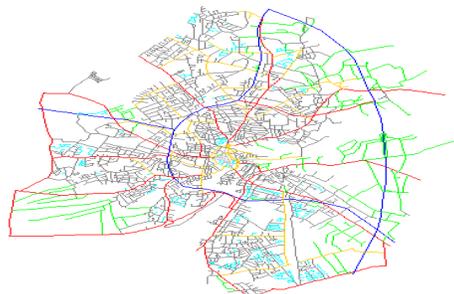


Figure 4. The simulation data sets are generated based on the city and its vicinity in Germany.

of  $c$ . We rank the probability  $Pr_a$  in descending order and pick the top- $x$  nodes in the sorted list as the key distributees.

2) *Association-rule-based Scheme*: Association rule technique is a well-known machine learning mechanism that can effectively discover hidden associations in the collection of data. In general, an association rule is defined as an expression  $X \Rightarrow Y$ , where  $X$  and  $Y$  are value set, with support  $s\%$ . It indicates the fact that  $X$  tends to be associated with  $Y$ , with the evidence that  $s\%$  of tuples contain both  $X$  and  $Y$ . We adapt it to our problem for finding  $x$  nodes that have associated moving patterns. To be more specific, we try to find the rule  $X \Rightarrow Y$  from  $D$  of the highest support  $s\%$ , where  $X = \{c\}$ , the current node that is looking for candidates from its current 1-hop neighborhood, and  $Y$  is a set of  $x$  nodes  $\{c_1, \dots, c_x\}$ , i.e. an  $x$ -node set. The rule indicates the fact that node  $c$  is moving together with nodes  $c_1, \dots, c_x$ . The support  $s\%$  equals to the number of time points at which both  $\{c\}$  and  $\{c_1, \dots, c_x\}$  locate in the 1-hop neighborhood.

There has been active research on efficient association rule mining algorithms. However, we cannot directly apply these algorithms to our problem, as they return the association rules whose supports are no less than a given threshold, while in our case, we look for the  $x$ -node association rule of the highest support, which is unknown before mining. If we set the threshold as 0, it will result in computing all possible  $\binom{t}{x}$  ( $t$ : number of candidate nodes) combinations of associations, which will be very expensive. Therefore, our goal is to efficiently discover the  $x$ -node association rule that is of the highest support from the trajectory data. If there are multiple such rules, we pick the one of the largest support, and choose the  $x$  nodes in the  $Y$  side of the rule.

The general principle of most of association rule mining algorithms for efficient mining is to make use of the *monotone* property of the association rules, which refers to the fact that any subset of a frequent itemset (i.e., of large support) must be frequent [2]. Thus generating the candidate itemsets in each pass only needs to use the frequent itemsets found in the previous pass. We utilize this property and design the following algorithm. First, given the current node  $c$  that is looking for candidates from its current 1-hop neighborhood, for each candidate

node  $c'$ , we compute the support of 1-node association  $\{c\} \Rightarrow \{c'\}$ , and rank these supports in descending order. Following the *monotone* property of association rules, the target  $x$ -node association of the top-1 support must be chosen from the 1-node associations of the top- $x$  support (i.e., the support of the top  $x$ -th item in the sorted item list). Therefore, we pick the 1-node associations of the top- $x$  support. If there are exactly  $x$  such nodes, they are the  $x$  key distributee nodes that we look for. Otherwise, out of the  $x' > x$  nodes, we compute the support for all possible  $x$ -node associations, and output the one of the largest support. Our algorithm only needs at most  $\binom{x'}{x}$  passes to find  $x$  key distributee nodes. Compared with checking all possible  $\binom{t}{x}$  ( $t > x'$ ) choices, where  $t$  is the set of all possible candidate nodes, our algorithm is much more efficient.

We use an example to illustrate our algorithm. Consider a collector node  $c_0$  whose neighborhood at various time points is shown in Table I (a). Assume  $x=3$ . We first calculate the support of all 1-node association, with the result shown in Table I (b). There are four nodes  $c_1, c_2, c_3$  and  $c_5$  that are of top-3 support 0.75. Then we calculate the support of  $\binom{4}{3} = 4$  possible 3-node sets. Table I (c) shows that out of these four candidates,  $\{c_1, c_2, c_5\}$  and  $\{c_2, c_3, c_5\}$  both have the same highest support value. We pick one and return it as the final result.

## VI. SIMULATION EVALUATION

In this section, we describe our simulation methodology and present the results that evaluate the effectiveness of our schemes.

### A. Methodology

We would like to evaluate the feasibility of applying our approaches in application environments (e.g. traffic monitoring in VANETs) using mobile wireless networks. Thus, we conducted simulations based on mobile devices generated from a city environment and its vicinity in Germany [7] as shown in Figure 4. The size of the area is  $25000m \times 25000m$ . We generated 1000 nodes and placed them randomly inside the city as a real-world network. To further simulate real-world scenarios, during

the simulation period some new nodes may move into the city environment and some existing nodes may move out the city environment. We studied two different scenarios with respect to the traveling speed of the node: walking speed (5ft/sec) and vehicular traveling speed (50ft/sec) by randomly choosing multiple subsets of nodes. The scenario using the regular walking speed simulates data collection through mobile phones carried by people, while the scenario with the vehicular traveling speed intends to study the applications enabled by the data collected through VANETs. There are no pre-defined trajectories for each node. However, group of nodes may travel together to common destinations (e.g. shopping malls or museums in the city).

### B. Metrics

We utilize the following metrics to evaluate the effectiveness of our key distribution schemes using neighborhood prediction:

**Prediction Accuracy.** We measure the effectiveness of the key distribution through neighborhood prediction. We split our simulation study time into two periods: *past* and *future*. The data in the *past* is used to perform prediction, whereas the data in the *future* is used to validate the prediction accuracy. For a given collector node, we define the *prediction accuracy* as the percentage of the intersection of the predicted devices that will travel together in the future ( $\{N_{predict}\}$ ) and the devices that are indeed traveling together in the future ( $\{N_{future}\}$ ):  $\frac{|\{N_{predict}\} \cap \{N_{future}\}|}{|\{N_{predict}\}|}$ . We will evaluate the effectiveness of our key distribution schemes by studying the statistical characteristics of the prediction accuracy through calculating its Cumulative Distribution Function (CDF) and averaged prediction error.

**Time Performance.** By measuring the time that each scheme needs to perform neighborhood prediction for key distribution, we evaluate the efficiency across different schemes. This metric helps to benchmark our schemes in the simulation environment and further indicates the feasibility of implementing them in real wireless devices.

### C. Results

1) **Prediction Accuracy: Cumulative Distribution Function (CDF) Measurement: 1-hop Scenario.** We are interested in studying what is the probability of different key distribution schemes that can perform neighborhood prediction with 100th, 75th, 50th, and 25th percentile accuracy. Figure 5 presents the CDF of prediction accuracy with respect to different  $m$  and  $n$  in the secret sharing method under the walking speed. In Figure 5,  $n$  is set to 15 and 50 respectively and  $m$  is set to 10 and 20 respectively. In this simulation setup,  $n$  is the network size and all the nodes are within the transmission range of the collector node. We observed that *Association-rule-based* scheme tops

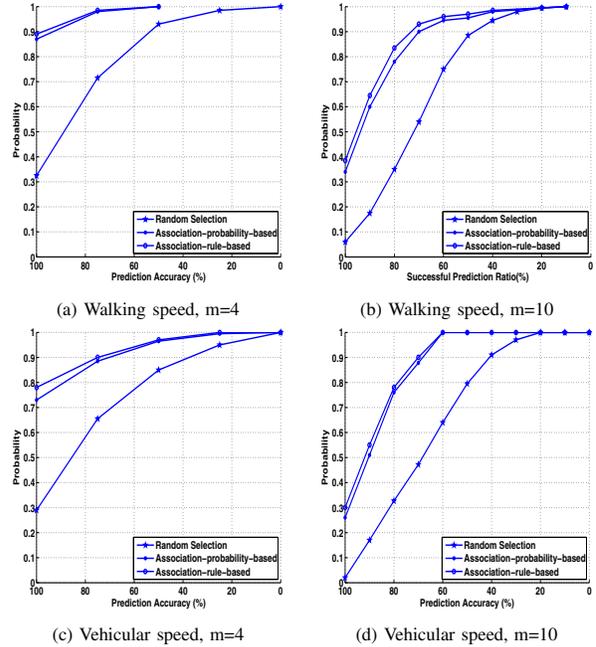


Figure 6. CDF of prediction accuracy under different traveling speed when  $n = 50$ .

out the performance, whereas *Random Selection* has the worst prediction performance. In general, Correlation-aware schemes outperform the Correlation-blind scheme.

Further, we found that under a fixed  $m$ , the larger the  $n$  is the higher the prediction accuracy can be achieved. Because under a larger  $n$ , there are more nodes that are holding key shares travel together with the collector node, and thus the probability of a successful key reconstruction is increased. On the other hand, under a fixed  $n$ , the smaller the  $m$  is the higher the prediction accuracy can be achieved. Because under a smaller  $m$ , it requires fewer nodes that are holding key shares travel together in order to achieve successful key reconstruction.

Figure 6 presents the comparison of the Prediction Accuracy CDFs under different traveling speed, walking speed and vehicular speed, with different setups of the secret sharing method, i.e., (4, 50) and (10, 50). We observed the similar performance trend as in Figure 5: Correlation-aware schemes outperform the Correlation-blind scheme. Further, the performance of our key distribution schemes under the vehicular speed is qualitatively the same as the performance under the walking speed. This indicates that our approach is generic across different device traveling speed.

**Averaged Prediction Error: 1-hop scenario.** Figure 7 (a) and (b) present the percentage of the prediction error versus different  $(m, n)$  setups in the secret sharing method across our key distribution schemes under the walking speed. We observed that Correlation-aware schemes incur smaller prediction errors (less than 36%) and the *Association-rule-based* scheme presents the smallest prediction errors in all cases. Further, under a fixed  $n$ , the prediction error increases with the

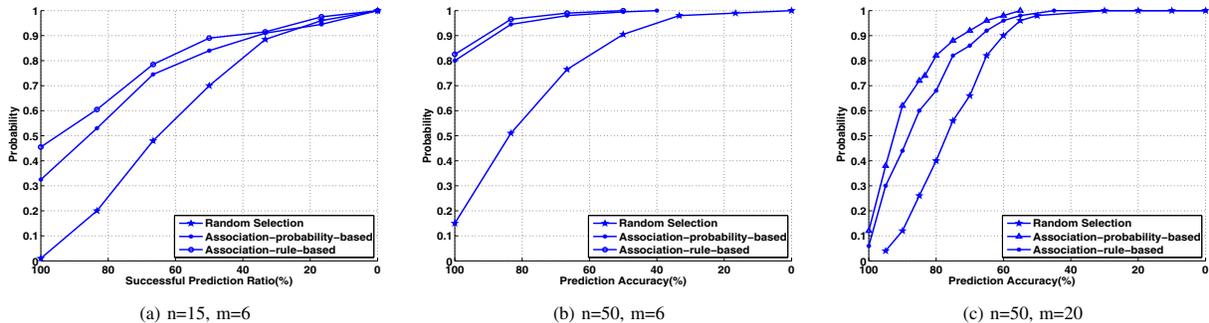


Figure 5. Cumulative Distribution Function(CDF) of prediction accuracy under the walking speed.

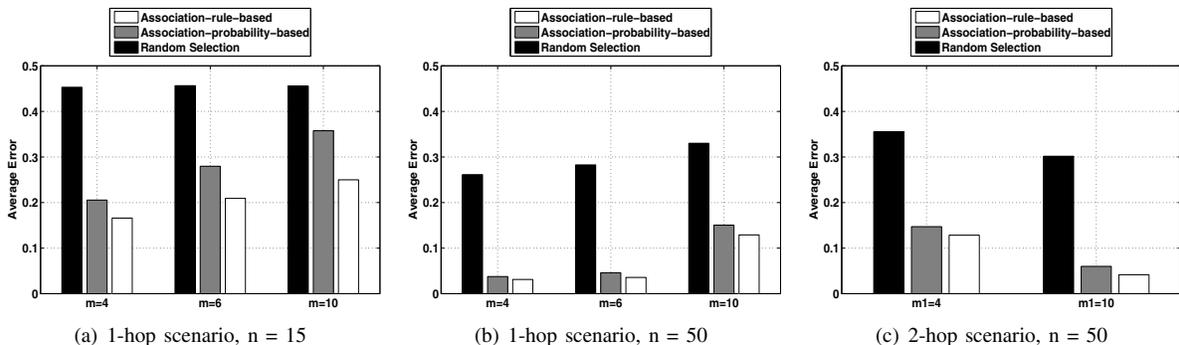


Figure 7. Averaged prediction error using TRAP under the walking speed.

increasing number of  $m$ . Overall, the results of averaged prediction errors are inline with the observations of prediction accuracy in Figure 5. This is encouraging as it indicates that our key distribution schemes are highly effective in distributing the key shares to those devices that are traveling together with the collector node.

**TRAP: 2-hop Scenario.** We next present the results when there are not enough devices within the transmission range of the collector node and the key distribution will be performed in the multi-hop range of the collector node. Figure 8 presents the CDF of the prediction accuracy for a (20, 50) secret sharing method in a 2-hop scenario. During key reconstruction, there are not enough key shares within the transmission range of the collector node that are traveling together with it, e.g.,  $m_1=4$  and 6 in this simulation. The rest of the key shares will be collected through the second hop of the collector node using TRAP. We found that the key distribution schemes have better performance when  $m_1 = 10$  as shown in Figure 8 (b) than those when  $m_1 = 4$  (Figure 8 (a)). This is because when there are more key shares can be found in the 1-hop range, there will be less nodes carrying key shares need to be found in the 2-hop range, and consequently the prediction accuracy increases. Further, when there are more key shares need to be collected in the 2-hop range, i.e.,  $m_1 = 4$ , the *Association-rule-based* scheme can still reach the probability of 84% to achieve the prediction accuracy of 80% or higher. Additionally, the results of the averaged prediction error shown in Figure 7 (c) are consistent with our prediction accuracy. Thus, these results provide strong evidence of

the effectiveness of TRAP.

**Time performance.** Finally, we study the time efficiency of our key distribution schemes. Table II presents the time measurements of our schemes when using various setups of  $m$  and  $n$  in the secret sharing method. We observed that the time to perform key distribution through neighborhood prediction is in the order of milliseconds for all the schemes by using a DELL desktop with Intel Core2 Q6600 2.4GHz processor. Further, we found that the schemes, e.g., *Association-rule-based* scheme, which provide higher prediction accuracy run slower. Thus, there exists a tradeoff between the prediction accuracy and the computation time. Our results will provide a guidance for choosing different schemes based on application needs in practice.

## VII. CONCLUSION

In this work, we proposed a fully decentralized key management framework to facilitate secure data access in mobile wireless networks, where cryptographic keys

Scheme setting	(4, 15)	(6, 15)	(10, 15)
Random Selection	10.2	10.48	11.06
Association-probability-based	27.8	31.4	44.6
Association-rule-based	29.2	33.0	46.2
Scheme setting	(4, 50)	(6, 50)	(10, 50)
Random Selection	13.6	14.08	14.6
Association-probability-based	42.2	41.4	48.6
Association-rule-based	44.3	45.8	49.7

Table II  
TIME PERFORMANCE (IN MILLISECOND) ACROSS DIFFERENT KEY DISTRIBUTION SCHEMES

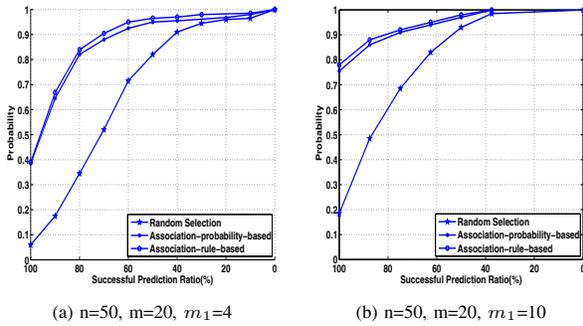


Figure 8. CDF of prediction accuracy under different traveling speed when  $n = 50$ .

are split into multiple shares and are distributed to multiple nodes in the network. The data is cached in the collecting mobile devices within the network to reduce the high communication overhead and excessive energy consumption among wireless devices if continuously forwarding the data to centralized storage nodes. To handle the node mobility, we further developed the Transitive Prediction (TRAP) protocol that distributes the key shares to the nodes that are moving together through neighborhood prediction for effective key reconstruction in mobile environments. Additionally, as a part of TRAP, we designed three key distribution schemes to choose the distributee nodes that have co-moving patterns by analyzing the correlation relationship embedded in the trajectories of co-moving devices. We further derived a theoretical analysis of the robustness of our approach. Our simulation results based on data sets generated from a simulated mobile wireless network in city environment demonstrated that our key distribution schemes are highly effective for key reconstruction. Both of our theoretical analysis and simulation results provide strong evidence of the feasibility of applying the decentralized key management framework to achieve resilient data confidentiality in distributed mobile environments. As a further goal, we plan to extend TRAP to the energy-constrained mobile computing model, and investigate the complexity and overhead of TRAP in terms of energy consumption.

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