

Assertion-based encapsulation and refinement of classes

David A. Naumann

Stevens Institute of Technology

Joint work with Mike Barnett and Anindya Banerjee

Supported by NSF CCR-0208984 and CCF-0429894.

Outline

- ◆ Difficulty in reasoning about object invariants due to callbacks and heap sharing (in sequential programs) —programmer's view, logician's view
- ◆ The boogie and friends disciplines: state based encapsulation (with Mike Barnett [LICS])
- ◆ Simulations (two-state invariants) —representation independence (with Anindya Banerjee)
- ◆ Application of simulation: observational purity
- ◆ Related work and Phd/postdoc advert

Programmer's intro: object invariants

```
class Subject {  
  private x,y: int := 0,1;  
  invariant  $\mathcal{I}(\text{self})$    where  $\mathcal{I}$  is defined by  $\mathcal{I}(o) = o.x < o.y$   
  method m() {  
    self.x := self.x+1;  
  
    self.y := self.y+1; } ... }
```

Programmer's intro: object invariants

```
class Subject {  
  private x,y: int := 0,1; obs: Observer :=...;  
  invariant  $\mathcal{I}(\text{self})$    where  $\mathcal{I}$  is defined by  $\mathcal{I}(o) = o.x < o.y$   
  method m() {  
    self.x := self.x+1;  
    obs.notify();  
    self.y := self.y+1; }   ... }
```

Programmer's intro: object invariants

```
class Subject {  
  private x,y: int := 0,1; obs: Observer :=...;  
  invariant  $\mathcal{I}(\text{self})$    where  $\mathcal{I}$  is defined by  $\mathcal{I}(o) = o.x < o.y$   
  method m() {  
    self.x := self.x+1;  
    obs.notify();  
    self.y := self.y+1; }    ... }  
class Observer {  
  z: Subject := ...;  
  method notify() { z.m(); }    ... }
```

Programmer's intro: object invariants

```
class Subject {  
  private x,y: int := 0,1; obs: Observer :=...;  
  invariant  $\mathcal{I}(\text{self})$    where  $\mathcal{I}$  is defined by  $\mathcal{I}(o) = o.x < o.y$   
  method m() {  
    self.x := self.x+1;  
    obs.notify();  
    self.y := self.y+1; } ... }  
class Observer {  
  z: Subject := ...;  
  method notify() { z.m(); } ... }
```

When should \mathcal{I} hold?

Programmer's intro (2): sharing

```
class Subject2 {  
  private x: Integer := new Integer(0);  
  private y: Integer := new Integer(1);  
  invariant  $\mathcal{I}(\text{self})$    where  $\mathcal{I}(o) = o.x.val < o.y.val$   
  method m() { self.x.incr(); self.y.incr(); }  
}
```

Programmer's intro (2): sharing

```
class Subject2 {  
  private x: Integer := new Integer(0);  
  private y: Integer := new Integer(1);  
  invariant  $\mathcal{I}(\text{self})$    where  $\mathcal{I}(o) = o.x.\text{val} < o.y.\text{val}$   
  method m() { self.x.incr(); self.y.incr(); }  
  method leak(): Integer { result := x; }    }  
class Main {  
  s: Subject2; i: Integer;  
  ... i := s.leak(); i.incr(); s.m() ... }
```


Programmer's intro (2): sharing

```
class Subject2 {  
  private x: Integer := new Integer(0);  
  private y: Integer := new Integer(1);  
  invariant  $\mathcal{I}(\text{self})$    where  $\mathcal{I}(o) = o.x.\text{val} < o.y.\text{val}$   
  method m() { self.x.incr(); self.y.incr(); }  
  method leak(): Integer { result := x; }    }  
class Main {  
  s: Subject2; i: Integer;  
  ... i := s.leak(); i.incr(); s.m() ... }
```

How can we encapsulate not just fields but also referenced objects?

Logician's intro

$$\frac{\{P \wedge \mathcal{I}\} \text{ body } \{Q \wedge \mathcal{I}\} \quad \mathcal{I} \text{ is encapsulated for } m}{\{P\} \text{ call } m() \{Q\}}$$

Declaration: $m()\{\text{body}\}$. *Specification* \mathcal{P} , \mathcal{Q} involves public fields; \mathcal{I} depends only on the internal representation.

Logician's intro

$$\frac{\{P \wedge \mathcal{I}\} \text{body} \{Q \wedge \mathcal{I}\} \quad \mathcal{I} \text{ is encapsulated for } m}{\{P\} \mathbf{call} \ m() \{Q\}}$$

Declaration: $m()\{\text{body}\}$. *Specification* \mathcal{P}, \mathcal{Q} involves public fields; \mathcal{I} depends only on the internal representation.

$$\frac{\{P\} S \{Q\} \quad S \text{ does not interfere}^* \text{ with } \mathcal{I}}{\{P \wedge \mathcal{I}\} S \{Q \wedge \mathcal{I}\}}$$

Logician's intro

$$\frac{\{P \wedge \mathcal{I}\} \text{body} \{Q \wedge \mathcal{I}\} \quad \mathcal{I} \text{ is encapsulated for } m}{\{P\} \mathbf{call} \ m() \{Q\}}$$

Declaration: $m()\{\text{body}\}$. *Specification* \mathcal{P}, \mathcal{Q} involves public fields; \mathcal{I} depends only on the internal representation.

$$\frac{\{P\} S \{Q\} \quad S \text{ does not interfere}^* \text{ with } \mathcal{I}}{\{P \wedge \mathcal{I}\} S \{Q \wedge \mathcal{I}\}}$$

* S does not write variables read in \mathcal{I} (hazard: aliased vars)

* S does not update objects read in \mathcal{I} (hazard: heap sharing)

Logicians' intro (2)

$$\frac{\frac{\{R \quad \} x := E \{P \quad \}}{\{P \quad \} \mathbf{call} \ m \ {Q \quad \}} \quad \frac{\{P \wedge I\} \text{body} \ {Q \wedge I\}}{\{P \quad \} \mathbf{call} \ m \ {Q \quad \}}}{\{R \quad \} x := E ; \mathbf{call} \ m \ {Q \quad \}}$$

⋮

Logicians' intro (2)

$$\frac{\frac{\{R\} x := E \{P\} \quad \text{no interference}}{\{R \wedge I\} x := E \{P \wedge I\}} \quad \frac{\frac{\{P \wedge I\} \text{ body } \{Q \wedge I\}}{\{P \wedge I\} \mathbf{call} \ m \ \{Q \wedge I\}}}{\{R \wedge I\} x := E ; \mathbf{call} \ m \ \{Q \wedge I\}}}{\vdots}$$

Logicians' intro (2)

$$\frac{\frac{\{R\} x := E \{P\} \quad \text{no interference}}{\{R \wedge I\} x := E \{P \wedge I\}} \quad \frac{\frac{\{P \wedge I\} \text{ body } \{Q \wedge I\}}{\{P \wedge I\} \mathbf{call} \ m \ \{Q \wedge I\}} \quad \vdots}{\{R \wedge I\} x := E ; \mathbf{call} \ m \ \{Q \wedge I\}} \quad \vdots}{\{R\} \text{ init}; \{R \wedge I\} x := E ; \mathbf{call} \ m \ \{Q \wedge I\} \Rightarrow \{Q\}}$$

Logicians' intro (2)

$$\begin{array}{c}
 \vdots \\
 \frac{\{R\} x := E \{P\} \quad \text{no interference}}{\{R \wedge I\} x := E \{P \wedge I\}} \qquad \frac{\{P \wedge I\} \text{ body } \{Q \wedge I\}}{\{P \wedge I\} \mathbf{call} \ m \ \{Q \wedge I\}} \\
 \hline
 \{R \wedge I\} x := E ; \mathbf{call} \ m \ \{Q \wedge I\} \\
 \vdots \\
 \{R\} \text{ init}; \{R \wedge I\} x := E ; \mathbf{call} \ m \ \{Q \wedge I\} \Rightarrow \{Q\}
 \end{array}$$

How generalize to multiple instantiation, i.e., $\mathcal{I}(o)$ for all o ?

Logicians' intro (2)

$$\begin{array}{c}
 \vdots \\
 \frac{\{R\} x := E \{P\} \quad \text{no interference}}{\{R \wedge I\} x := E \{P \wedge I\}} \qquad \frac{\{P \wedge I\} \text{ body } \{Q \wedge I\}}{\{P \wedge I\} \mathbf{call} \ m \ \{Q \wedge I\}} \\
 \hline
 \{R \wedge I\} x := E ; \mathbf{call} \ m \ \{Q \wedge I\} \\
 \vdots \\
 \{R\} \text{ init}; \{R \wedge I\} x := E ; \mathbf{call} \ m \ \{Q \wedge I\} \Rightarrow \{Q\}
 \end{array}$$

How generalize to multiple instantiation, i.e., $\mathcal{I}(o)$ for all o ?

What about outcalls in `body`, i.e. method invocations on other objects, which may lead to reentrant callbacks?

Logicians' intro (2)

$$\begin{array}{c}
 \vdots \\
 \frac{\{R\} x := E \{P\} \quad \text{no interference}}{\{R \wedge I\} x := E \{P \wedge I\}} \qquad \frac{\{P \wedge I\} \text{ body } \{Q \wedge I\}}{\{P \wedge I\} \mathbf{call} \ m \ \{Q \wedge I\}} \\
 \hline
 \{R \wedge I\} x := E ; \mathbf{call} \ m \ \{Q \wedge I\} \\
 \vdots
 \end{array}$$

$$\{R\} \text{ init}; \{R \wedge I\} x := E ; \mathbf{call} \ m \ \{Q \wedge I\} \Rightarrow \{Q\}$$

How generalize to multiple instantiation, i.e., $\mathcal{I}(o)$ for all o ?

What about outcalls in `body`, i.e. method invocations on other objects, which may lead to reentrant callbacks?

How express absence of interference due to heap sharing?

An assertion-based discipline

Problems:

- ◆ due to reentrant callbacks, precondition $\mathcal{P} \wedge \mathcal{I}$ for body is unsound unless \mathcal{I} re-established before outcalls

An assertion-based discipline

Problems:

- ◆ due to reentrant callbacks, precondition $\mathcal{P} \wedge \mathcal{I}$ for body is unsound unless \mathcal{I} re-established before outcalls
- ◆ need to protect $\mathcal{I}_{\text{Subject}}(o)$ from interference —by code in other classes and by other instances $p \neq o$ of Subject

An assertion-based discipline

Problems:

- ◆ due to reentrant callbacks, precondition $\mathcal{P} \wedge \mathcal{I}$ for body is unsound unless \mathcal{I} re-established before outcalls
- ◆ need to protect $\mathcal{I}_{\text{Subject}}(o)$ from interference —by code in other classes and by other instances $p \neq o$ of Subject

Solution uses a single everywhere-invariant, \mathcal{PI} .

$$\text{Rule: } \frac{\{\mathcal{PI} \wedge \mathcal{P}\} S \{Q\}}{\{\mathcal{P}\} S \{Q\}}.$$

An assertion-based discipline

Problems:

- ◆ due to reentrant callbacks, precondition $\mathcal{P} \wedge \mathcal{I}$ for body is unsound unless \mathcal{I} re-established before outcalls
- ◆ need to protect $\mathcal{I}_{\text{Subject}}(o)$ from interference —by code in other classes and by other instances $p \neq o$ of Subject

Solution uses a single everywhere-invariant, \mathcal{PI} .

Rule: $\frac{\{\mathcal{PI} \wedge \mathcal{P}\} S \{Q\}}{\{\mathcal{P}\} S \{Q\}}$. Handles transfer and sharing of

objects across encapsulation boundaries. Can use with standard logics and type systems.

Auxiliary field to make explicit when invariant holds:

*inv : **boolean** := false*

Maintain program invariant $PI : (\forall o \bullet o.inv \Rightarrow \mathcal{I}_{type(o)}(o))$

Auxiliary field to make explicit when invariant holds:

inv : **boolean** := false

Maintain program invariant $PI : (\forall o \bullet o.inv \Rightarrow \mathcal{I}_{type(o)}(o))$

class Subject { ...

invariant $\mathcal{I}_{Subject}(self)$ where $\mathcal{I}_{Subject}(o) = o.x < o.y$

method m() {

assert self.inv (* precondition *)

unpack self; (* self.inv := false *)

self.x := self.x+1; obs.notify(); self.y := self.y+1; (* $\mathcal{I}(self)$ *)

pack self; (* self.inv := true *) } ... }

class Main ... **method** notify() { **assert** z.inv ?; z.m(); }

Auxiliary field to make explicit when invariant holds:

inv : **boolean** := false

Maintain program invariant $PI : (\forall o \bullet o.inv \Rightarrow \mathcal{I}_{type(o)}(o))$

class Subject { ...

invariant $\mathcal{I}_{Subject}(self)$ where $\mathcal{I}_{Subject}(o) = o.x < o.y$

method m() {

assert self.inv (* precondition *)

unpack self; (* self.inv := false *)

self.x := self.x+1; obs.notify(); self.y := self.y+1; (* $\mathcal{I}(self)$ *)

pack self; (* self.inv := true *) } ... }

class Main ... **method** notify() { **assert** z.inv ?; z.m(); }

Absence of interf., as a precond.: $\{\neg v.inv \wedge PI\} v.f := E \{PI\}$

Auxiliary field to delimit heap dependence of invariant:

own : Object := null

Def: $o \preceq p$ iff either $o = p.\text{own}$ or $o \preceq p.\text{own}$.

Auxiliary field to delimit heap dependence of invariant:

own : Object := null

Def: $o \preceq p$ iff either $o = p.\text{own}$ or $o \preceq p.\text{own}$.

*Def: \mathcal{I}_C is **admissible** iff*

when $\mathcal{I}_C(o)$ depends on $p.f$ then either $o = p$ or $o \preceq p$.

Auxiliary field to delimit heap dependence of invariant:

own : Object := null

Def: $o \preceq p$ iff either $o = p.\text{own}$ or $o \preceq p.\text{own}$.

*Def: \mathcal{I}_C is **admissible** iff*

when $\mathcal{I}_C(o)$ depends on $p.f$ then either $o = p$ or $o \preceq p$.

Absence of interference, as a precondition:

$\{\neg v.\text{inv} \wedge (\forall o \bullet o \preceq v \Rightarrow \neg o.\text{inv}) \wedge \mathcal{PI}\} v.f := E \{\mathcal{PI}\}$

Ownership provides stateful encapsulation: $\neg o.\text{inv}$ means control is inside the boundary for o .

Last auxiliary field for ownership discipline:

`com : boolean := false`

$\mathcal{PI} : (\forall o \bullet o.inv \Rightarrow \mathcal{I}_{type(o)}(o)) \wedge$

$(\forall o \bullet o.inv \Rightarrow (\forall p \bullet p.own = o \Rightarrow p.com)) \wedge$

$(\forall o \bullet o.com \Rightarrow o.inv)$

Last auxiliary field for ownership discipline:

`com : boolean := false`

$\mathcal{PI} : (\forall o \bullet o.inv \Rightarrow \mathcal{I}_{type(o)}(o)) \wedge$

$(\forall o \bullet o.inv \Rightarrow (\forall p \bullet p.own = o \Rightarrow p.com)) \wedge$

$(\forall o \bullet o.com \Rightarrow o.inv)$

Absence of interf., as a precondition: $\{ \neg v.inv \wedge \mathcal{PI} \} v.f := E \{ \mathcal{PI} \}$

Last auxiliary field for ownership discipline:

`com : boolean := false`

$\mathcal{PI} : (\forall o \bullet o.inv \Rightarrow \mathcal{I}_{type(o)}(o)) \wedge$

$(\forall o \bullet o.inv \Rightarrow (\forall p \bullet p.own = o \Rightarrow p.com)) \wedge$

$(\forall o \bullet o.com \Rightarrow o.inv)$

Absence of interf., as a precond.: $\{ \neg v.inv \wedge \mathcal{PI} \} v.f := E \{ \mathcal{PI} \}$

*Precondition and effect of **unpack** E:*

assert $E.inv \wedge \neg E.com$;

$E.inv := false$; **forall** o **with** $o.own = E$ **do** $o.com := false$;

Last auxiliary field for ownership discipline:

`com : boolean := false`

$\mathcal{PI} : (\forall o \bullet o.inv \Rightarrow \mathcal{I}_{type(o)}(o)) \wedge$

$(\forall o \bullet o.inv \Rightarrow (\forall p \bullet p.own = o \Rightarrow p.com)) \wedge$

$(\forall o \bullet o.com \Rightarrow o.inv)$

Absence of interf., as a precond.: $\{ \neg v.inv \wedge \mathcal{PI} \} v.f := E \{ \mathcal{PI} \}$

*Precondition and effect of **unpack** E:*

assert E.inv \wedge \neg E.com;

E.inv := false; **forall** o **with** o.own = E **do** o.com := false;

*Precondition and effect of **pack** E:*

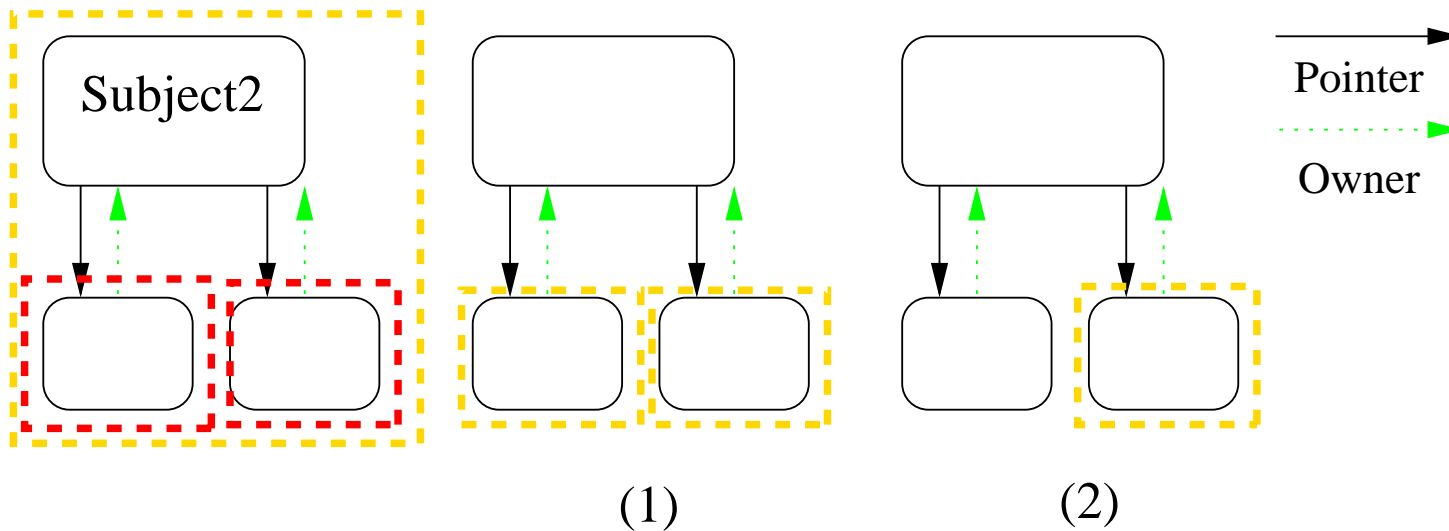
assert \neg E.inv \wedge $\mathcal{I}_{type(E)}(E)$;

E.inv := true; **forall** o **with** o.own = E **do** o.com := true;


```

class Subject2 ... method m() { assert inv $\wedge$  $\neg$ comm
    unpack self; (1)
    unpack x; (2)
    x.value:=x.value+1; ...

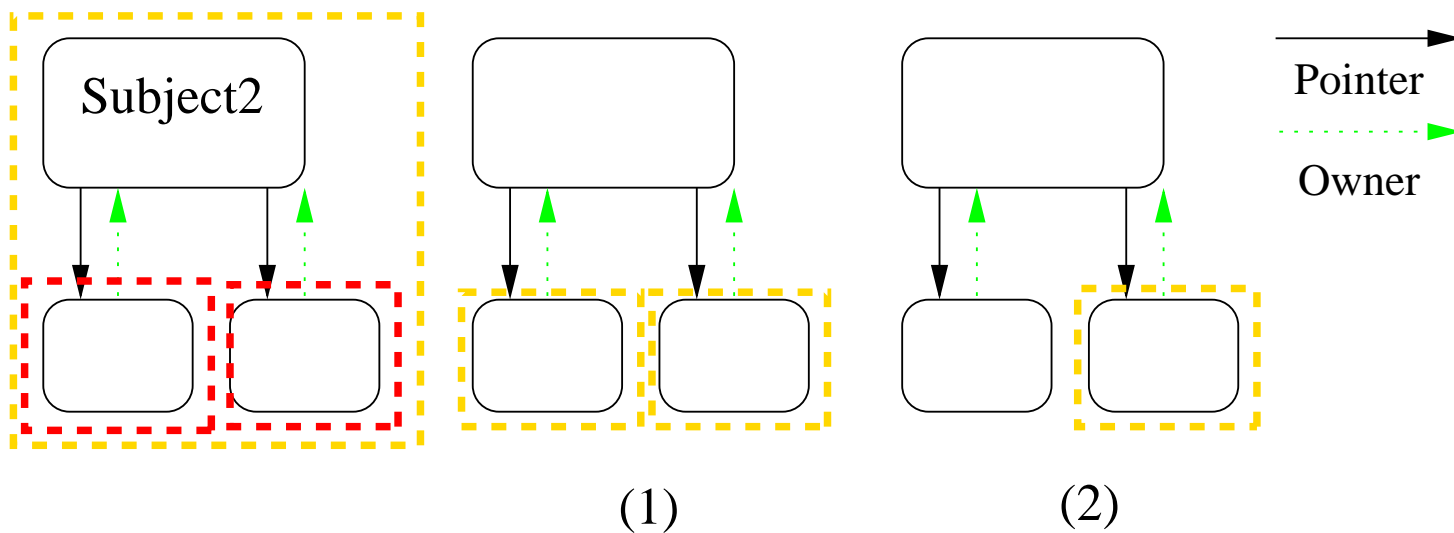
```



```

class Subject2 ... method m() { assert inv $\wedge$  $\neg$ comm
    unpack self; (1)
    unpack x; (2)
    x.value:=x.value+1; ...

```



Encapsulation is hierarchical. But hierarchy is mutable...

Ownership transfer

$\{\neg v.\text{inv} \wedge \neg E.\text{inv} \wedge \mathcal{PI}\} v.\text{own} := E \{\mathcal{PI}\}$

*Special command **setowner**; only manipulates auxiliary state, like **unpack/pack**.*

Ownership transfer

$\{\neg v.\text{inv} \wedge \neg E.\text{inv} \wedge \mathcal{PI}\} v.\text{own} := E \{\mathcal{PI}\}$

*Special command **setowner**; only manipulates auxiliary state, like **unpack/pack**.*

State-based encapsulation (vs. type systems):

- ◆ *avoids restriction on existence or reading of references*
- ◆ *allows transfer of objects across boundaries*
- ◆ *examples: lexer/stream, AST (into); tasks (between); database connections, malloc/free (in and out)*

Subclassing

$o.inv$ is a classname and $o.own$ is (object,classname).

$$\begin{aligned} \mathcal{PI} : & (\forall o \bullet o.inv \geq type(o)) \wedge \\ & (\forall o \bullet o.inv \leq C \Rightarrow \mathcal{I}_C(o)) \wedge \\ & (\forall o \bullet o.inv \leq C \Rightarrow (\forall p \bullet p.own = (o, C) \Rightarrow p.com)) \wedge \\ & (\forall o \bullet o.com \Rightarrow o.inv) \end{aligned}$$

*Precondition and effect of **pack** E to C:*

assert $E.inv = super(C) \wedge \mathcal{I}_C(E)$;

$E.inv := C$; **forall** o **with** $o.own = E$ **do** $o.com := true$;

Stateful encapsulation I.

Def: S is *properly annotated* iff each **pack**, **unpack**, **setowner**, and field update has stipulated precondition.

Theorem: $\{PI\} S \{PI\}$ for any properly annotated S .

Corollary: $\frac{\{PI \wedge P\} S \{Q\}}{\{P\} S \{Q\}}$ for all S, P, Q

Proof: Using a straightforward denotational semantics for a sequential language with mutually recursive class declarations and methods etc.

Stateful encapsulation II –sharing.

A List owns its nodes. A node does not own its neighbors.

```
class List {  
  head: ListNode;  
  invariant self.head=null  $\vee$  self.head.prev=null;  ... }  
class ListNode {  
  next, prev: ListNode;  
  invariant self.next=null  
     $\vee$  (self.next.prev=self  $\wedge$  self.next.own=self.own);  ... }
```

Stateful encapsulation II –sharing.

A List owns its nodes. A node does not own its neighbors.

```
class List {  
  head: ListNode;  
  invariant self.head=null  $\vee$  self.head.prev=null; ... }  
class ListNode {  
  next, prev: ListNode;  
  invariant self.next=null  
     $\vee$  (self.next.prev=self  $\wedge$  self.next.own=self.own); ... }
```

Decentralized invariants express acyclicity without induction.

Well behaved interaction —sharing, not separation.

Absence of interference, as a precondition:

$\{\neg v.\text{inv} \wedge$

$(\forall o \bullet \text{“}\mathcal{I}_C(o) \text{ depends on } v.f\text{”} \Rightarrow \neg o.\text{inv} \vee \mathcal{I}_C(o)[E/v.f])\}$

$v.f := E$

Absence of interference, as a precondition:

$\{\neg v.\text{inv} \wedge$

$(\forall o \bullet \text{“}\mathcal{I}_C(o) \text{ depends on } v.f\text{”} \Rightarrow \neg o.\text{inv} \vee \mathcal{I}_C(o)[E/v.f])\}$

$v.f := E$

Auxiliary field for friendship discipline:

$\text{deps} : \mathbf{set\ of\ Object} := \emptyset$

$(\forall o \bullet o \in v.\text{deps} \Rightarrow \neg o.\text{inv} \vee \mathcal{I}_C(o)[E/v.f])$

Absence of interference, as a precondition:

$\{\neg v.\text{inv} \wedge$

$(\forall o \bullet \text{“}\mathcal{I}_C(o) \text{ depends on } v.f\text{”} \Rightarrow \neg o.\text{inv} \vee \mathcal{I}_C(o)[E/v.f])\}$

$v.f := E$

Auxiliary field for friendship discipline:

$\text{deps} : \text{set of Object} := \emptyset$

$(\forall o \bullet o \in v.\text{deps} \Rightarrow \neg o.\text{inv} \vee \mathcal{I}_C(o)[E/v.f])$

Admissibility: when $\mathcal{I}_C(o)$ depends on $p.f$ then either $o = p$, $o \preceq p$, or $p = o.g$ for some declared pivot g and $o \in p.\text{deps}$

Absence of interference, as a precondition:

$\{\neg v.\text{inv} \wedge$

$(\forall o \bullet \text{“}\mathcal{I}_C(o) \text{ depends on } v.f\text{”} \Rightarrow \neg o.\text{inv} \vee \mathcal{I}_C(o)[E/v.f])\}$

$v.f := E$

Auxiliary field for friendship discipline:

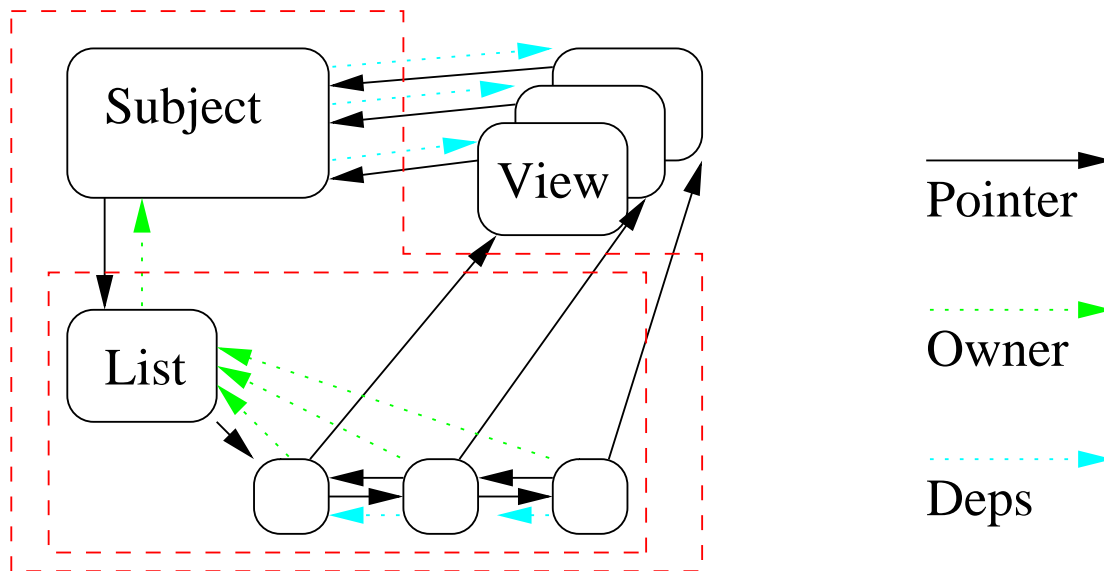
deps : set of Object := \emptyset

$(\forall o \bullet o \in v.\text{deps} \Rightarrow \neg o.\text{inv} \vee \mathcal{I}_C(o)[E/v.f])$

*Admissibility: when $\mathcal{I}_C(o)$ depends on $p.f$ then either $o = p$, $o \preceq p$, or **$p = o.g$** for some declared pivot **g** and **$o \in p.\text{deps}$***

Abstract from $\mathcal{I}_C(o)[E/v.f]$ as $\mathcal{U}_C(o, v, E)$.

Obligation: $\{\mathcal{I}_C(\text{self}) \wedge \mathcal{U}(\text{self}, g, \text{val})\}$ self.g.f := val $\{\mathcal{I}_C(\text{self})\}$



```

class Subject3 { val: int; (*state*) vsn: int; (*for sync*)
    friend View reads vsn, val; ... }
class View { version: int; private s: Subject; cache: int;
    invariant s.vsn-1 ≤ version ≤ s.vsn ∧
    (s.vsn=version ⇒ cache=s.val);
    guard s.vsn:=α by α - 1 ≤ version ≤ α; ... }

```

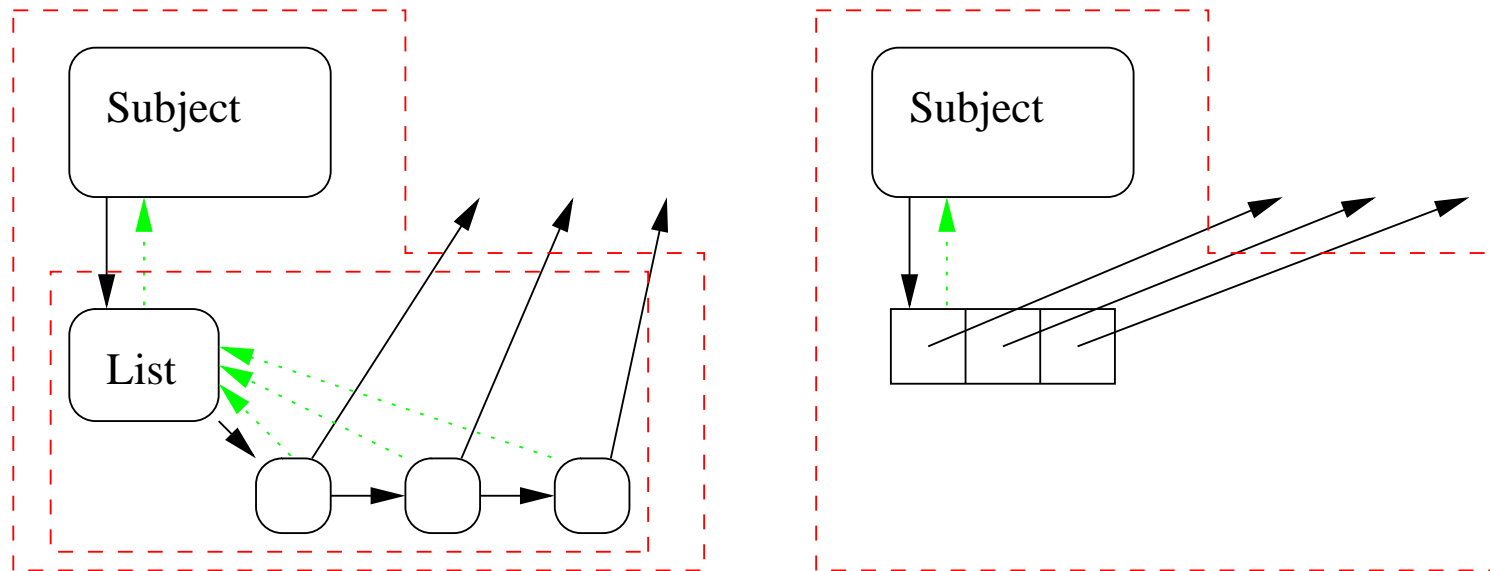
Encapsulation: rep. independence

```
class Subject2 {  
  private x: Integer := new Integer(0);  
  private y: Integer := new Integer(1);  
  invariant  $\mathcal{I}(\text{self})$    where  $\mathcal{I}(o) = o.x.val < o.y.val$   
  method m() { self.x.incr(); self.y.incr(); }
```

```
class Subject2 { // Alternate version  
  private x: int := 0;  
  private z: int := 1;  
  invariant  $\mathcal{I}(\text{self})$    where  $\mathcal{I}(o) = 0 < o.z$   
  method m() { self.x := self.x + 1; }
```

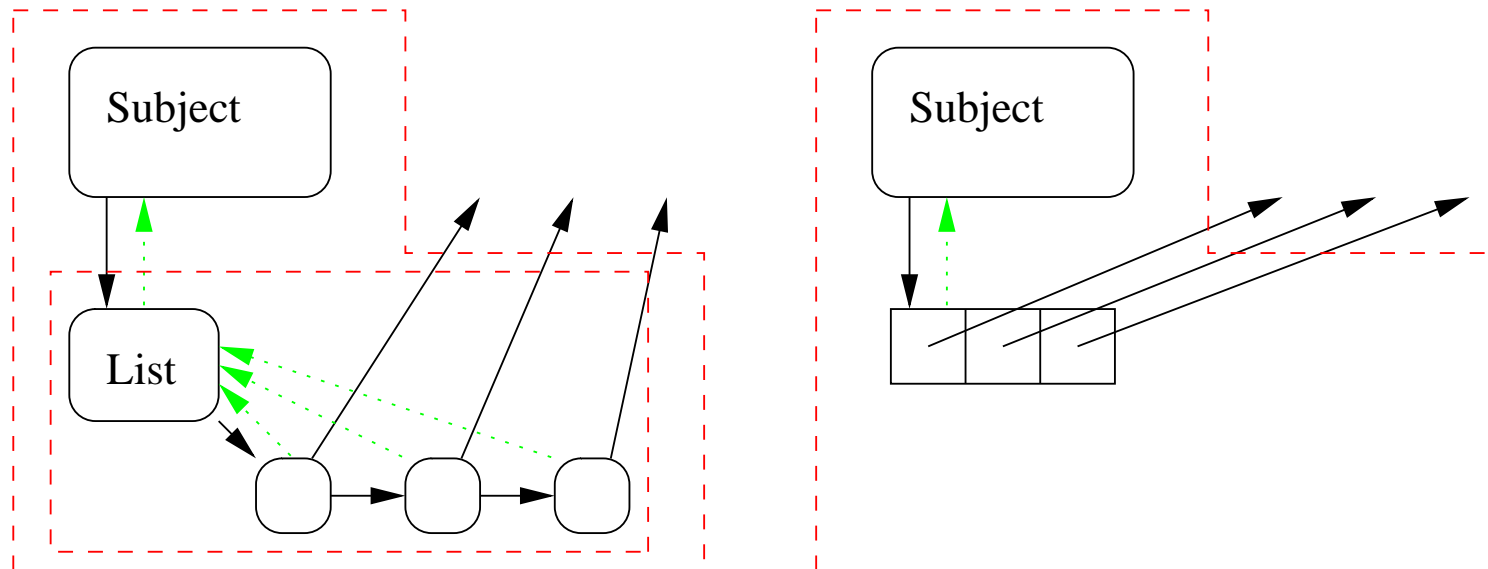
Coupling relation: $o.x.val = o'.x \wedge o.y.val - o.x.val = o'.z$

Towards modular coupling



Coupling relation: $\text{elts}(o.\text{list}) = \text{elts}(o'.\text{arr})$

Towards modular coupling

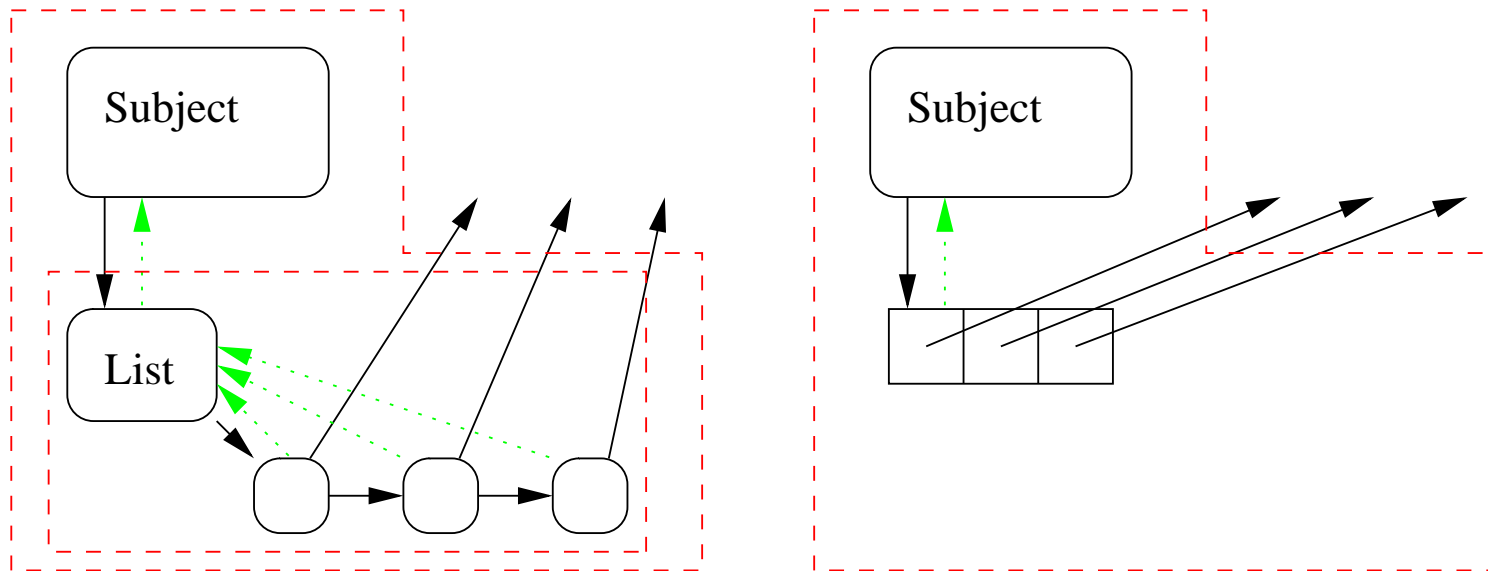


Coupling relation: $\text{elts}(o.\text{list}) = \text{elts}(o'.\text{arr})$

Partition $h = Xh * \text{Island}_1 * \dots * \text{Island}_k$

where $\text{Island}_i = (\text{instance } o_i \text{ of Subject}) * (\text{owned by } o_i)$.

Towards modular coupling



Coupling relation: $\text{elts}(o.\text{list}) = \text{elts}(o'.\text{arr})$

Partition $h = Xh * \text{Island}_1 * \dots * \text{Island}_k$

where $\text{Island}_i = (\text{instance } o_i \text{ of Subject}) * (\text{owned by } o_i)$.

Then $h \models \mathcal{I}(o_i)$ iff $\text{Island}_i \models \mathcal{I}(o)$ for admissible \mathcal{I} .

Coupling

Heaps h, h' coupled just if there are same-length partitions

$$h = Xh * \text{Island}_1 * \dots * \text{Island}_k$$

$$h' = Xh' * \text{Island}'_1 * \dots * \text{Island}'_k$$

Coupling

Heaps h, h' coupled just if there are same-length partitions

$$h = Xh * \text{Island}_1 * \dots * \text{Island}_k$$

$$h' = Xh' * \text{Island}'_1 * \dots * \text{Island}'_k$$

and for each i we have

$$o_i.\text{inv} = o'_i.\text{inv} \text{ and}$$

$o_i.\text{inv}$ implies Island_i coupled with Island'_i

(by the given [single-instance coupling](#)).

Coupling

Heaps h, h' coupled just if there are same-length partitions

$$h = Xh * \text{Island}_1 * \dots * \text{Island}_k$$

$$h' = Xh' * \text{Island}'_1 * \dots * \text{Island}'_k$$

and for each i we have

$$o_i.\text{inv} = o'_i.\text{inv} \text{ and}$$

$o_i.\text{inv}$ implies Island_i coupled with Island'_i

(by the given [single-instance coupling](#)).

Moreover $Xh \sim Xh'$ (modulo bijective renaming).

Coupling

Heaps h, h' coupled just if there are same-length partitions

$$h = Xh * \text{Island}_1 * \dots * \text{Island}_k$$

$$h' = Xh' * \text{Island}'_1 * \dots * \text{Island}'_k$$

and for each i we have

$$o_i.\text{inv} = o'_i.\text{inv} \text{ and}$$

$o_i.\text{inv}$ implies Island_i coupled with Island'_i

(by the given [single-instance coupling](#)).

Moreover $Xh \sim Xh'$ (modulo bijective renaming).

Identity on visible state (fields in Xh , interface of o_i).

Abstraction theorem

Theorem If the induced coupling is a *simulation*, i.e., is preserved by the methods of the revised class A , then it is preserved by all properly annotated contexts.

Abstraction theorem

Theorem If the induced coupling is a *simulation*, i.e., is preserved by the methods of the revised class A , then it is preserved by all properly annotated contexts.

Corollary: proof of program equivalence.

Abstraction theorem

Theorem If the induced coupling is a *simulation*, i.e., is preserved by the methods of the revised class A , then it is preserved by all properly annotated contexts.

Corollary: proof of program equivalence.

Reentrant callbacks and invariants/simulations: a method that does not require inv cannot rely on \mathcal{I} but may later reestablish \mathcal{I} —need modifies-specs of called methods.

Adaptations for simulation

- read fields of objects owned by an A : only in code of A
- Pack self to A : only in code of A , as it restores coupling.
- owner transfer: export of A 's reps only by code of A

Stronger alias control than for invariants, but only for A .

Observational purity

```
class View {  
  version: int; private s: Subject; cache: int; pending: bool  
  notify() { pending:=true; }  
  pure get(): int {  
    if pending then cache:=s.val endif; return cache; ... }  
}
```

Observational purity

```
class View {  
  version: int; private s: Subject; cache: int; pending: bool  
  notify() { pending:=true; }  
  pure get(): int {  
    if pending then cache:=s.val endif; return cache; ... }  
}
```

Use simulation to prove equivalent to an implementation in which get is strongly pure.

Observational purity

```
class View {  
  version: int; private s: Subject; cache: int; pending: bool  
  notify() { pending:=true; }  
  pure get(): int {  
    if pending then cache:=s.val endif; return cache; ... }  
}
```

Use simulation to prove equivalent to an implementation in which get is strongly pure.

skip \approx **assert** x.get() = 0 outside class View

Conclusion

- ◆ Discipline for control of dependence for object invariants. Controls use of pointers rather than their existence.
- ◆ Handles difficult design patterns that are common in practice, including cooperative sharing.
- ◆ No commitment to particular program logic or verification system.
- ◆ Uses verification conditions; not special type annotation but not fully automated.

Future work

- ◆ *precise* comparison with Separation Logic:

$$\frac{\{P\} m \{Q\} \vdash \{P'\} S \{Q'\}}{\{P * I\} \text{ body } \{Q * I\} \vdash \{P' * I\} S \{Q' * I\}}$$

- ◆ implementation, case studies, concurrency —Spec# project
- ◆ friends generalized to multi-class patterns
- ◆ integrate with ownership typing, extend to concurrency and refinement
- ◆ machine check soundness proofs

Related work

- ◆ Leino et al [JoT, ECOOP04, CASSIS04, Statics]
- ◆ O'Hearn et al [POPL04]; Mijajlović et al [FSTTCS 04]
–static modularity for separation logic
- ◆ Hongseok Yang [TCS?] –relational sep. logic
- ◆ full logic and mechanization —Pierik and de Boer

Advert

Seeking PhD student or postdoc to develop these ideas in context of JML, a specification language used by ESC/Java and several other systems e.g. smartcard verific. (Joint project with Iowa State (Gary Leavens) and UFPE, Recife, Brazil.)

References

Barnett, DeLine, Fähndrich, Leino, Schulte: *Verification of object-oriented programs with invariants* (JoT '04)

Leino, Müller: *Object invariants in dynamic contexts* (ECOOP'04)

Barnett, DN: *Friends need a bit more* (MPC'04); (LICS'04)

Pierik, Clarke, de Boer: *Creational invariants* (FTfJP'04)

O'Hearn, Yang, Reynolds: *Separation and Info Hiding* (POPL'04)

Banerjee and DN: *State based ownership and encapsulation for generic classes*

DN: *Observational purity and encapsulation*

Calcagno, O'Hearn, Bornat: *Program logic and equiv. vs. garbage*

(TCS03)